# Validation Report

# Michigan, SPS-1 Task Order 22, CLIN 2 October 2 to 3, 2007

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#### 1 Executive Summary

A visit was made to the Michigan 0100 on October 2 to 3, 2007 for the purposes of conducting a validation of the WIM system located on US Route 27 approximately 2.6 miles north of M-21. The SPS-1 is located in the righthand, southbound lane of a fourlane divided facility. The posted speed limit at this location is 60 mph for trucks. The LTPP lane is one of 4 lanes instrumented at this site. The validation procedures were in accordance with LTPP's SPS WIM Data Collection Guide dated August 21, 2001.

This is the third validation visit to this location. This is the original site location. It was installed in June 2005 by the agency.

This site meets all LTPP precision requirements except speed. This is not considered sufficient to disqualify the site as having research quality data. The classification algorithm currently does not provide research quality classification information.

The site is instrumented with quartz piezo sensors and DAW 190 electronics. It is installed in portland cement concrete, 400 feet long.

The validation used the following trucks:

- 1) 5-axle tractor-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 75,700 lbs., the "golden" truck.
- 2) 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 65,390 lbs., the "partial" truck.

The validation speeds ranged from 49 to 70 miles per hour. The agency had already identified that the 85<sup>th</sup> percentile speed for trucks was in excess to the posted speed limit of 60 mph for trucks. The Agency received approval from the Motor Carrier Enforcement Group to run the test trucks at speeds greater than the posted truck speed limit. The test trucks were not allowed to exceed the speeds being driven by the surrounding traffic. The pavement temperatures ranged from 62 to 86 degrees Fahrenheit. The desired speed range was achieved during this validation. The desired 30 degree Fahrenheit temperature range was not achieved.

Table 1-1 Post-Validation results – 260100 – 03-Oct-2007

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$5.5 \pm 7.0\%$	Pass
Tandem axles	±15 percent	$-1.5 \pm 6.1\%$	Pass
GVW	±10 percent	$-0.5 \pm 4.3\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.4 \pm 1.2 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

The pavement condition appeared to be satisfactory for conducting a performance evaluation. There were no distresses observed that would influence truck motions significantly. A visual survey determined that there is no discernable bouncing or avoidance by trucks in the sensor area. There has been no profile information collected in the year prior to the validation so WIMIndex values could not be computed. When profile data becomes available an amended report will be submitted that includes WIMIndex values.

If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 1-2 Results Based on ASTM E-1318-02 Test Procedures

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

This site needs four years of data to meet the goal of five years of research quality data.

#### 2 Corrective Actions Recommended

The pavement in the area of the trailing WIM sensor has developed a crack that runs laterally through the sensor installation and may have been the cause for the sensor's input cable to lose insulation resistance properties. The trailing sensor needs to be replaced.

There are no other corrective measures recommended for this site at this time under the assumption that LTPP will only recognize misclassification of heavy vehicles (FHWA Classes 6 and higher).

## **3 Post Calibration Analysis**

This final analysis is based on test runs conducted Oct 3, 2007 during the morning and early afternoon hours at test site 260100 on US Route 27. This SPS-1 site is on the southbound, righthand of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for the calibration and for the subsequent validation included:

- 1. 5-axle tractor-trailer with a tractor having an air suspension and trailer with a standard rear tandem and air suspension loaded to 75,700 lbs., the "golden" truck.
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 65,390 lbs., the "partial" truck.

Each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 49 to 70 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 62 to 86 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was not achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 3-1.

As shown in Table 3-1, the site meets and passed all LTPP performance criteria for research quality data for weight and spacing. It did not meet the requirements for speed, which is not considered sufficient to disqualify the site as having research quality data.

**Table 3-1 Post-Validation Results – 260100 – 03-Oct-2007** 

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$5.5 \pm 7\%$	Pass
Tandem axles	±15 percent	$-1.5 \pm 6.1\%$	Pass
GVW	±10 percent	$-0.5 \pm 4.3\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	$0.4 \pm 1.2 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during morning and early afternoon hours under mostly cloudy weather conditions, resulting in a limited range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the data set was split into three speed groups and two temperature groups. The distribution of runs by speed and temperature is illustrated in Figure 3-1. The figure indicates that the desired distribution of speed and temperature combinations was not achieved for this set of validation runs because of the limited temperature range.

The three speed groups were divided as follows: Low speed – 49 to 55 mph, Medium speed -56 to 62 mph and High speed -63 + mph. The two temperature groups were created by splitting the runs between those at 62 to 73 degrees Fahrenheit for Low temperature and 74 to 86 degrees Fahrenheit for High temperature.

# **Speed versus Temperature Combinations** 75 70 Speed (mph) comb. 55 50 45 70 75 85 60

Temperature (F)

Figure 3-1 Post-Validation Speed-Temperature Distribution – 260100 – 03-Oct-2007

A series of graphs was developed to investigate visually any sign of a relationship between speed or temperature and the scale performance.

Figure 3-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it can be seen that the GVW error estimate of the WIM equipment progresses from a slight underestimation at lower speeds toward a slight overestimation as speeds reach the higher end of the test range. The scatter of the percent error appears to be greater at the lower speeds.



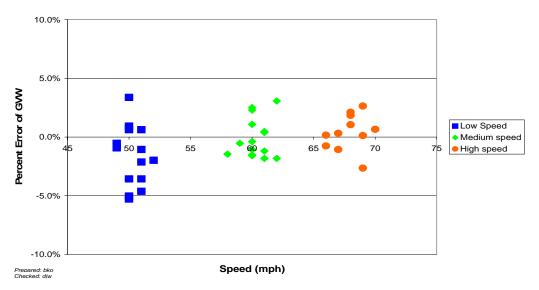


Figure 3-2 Post-validation GVW Percent Error vs. Speed – 260100 – 03-Oct-2007

Figure 3-3 shows the relationship between temperature and GVW percentage error. The graph illustrates that there does not appear to be a significant relationship between GVW error and pavement temperature although there is a tendency to underestimate at the lower temperatures.

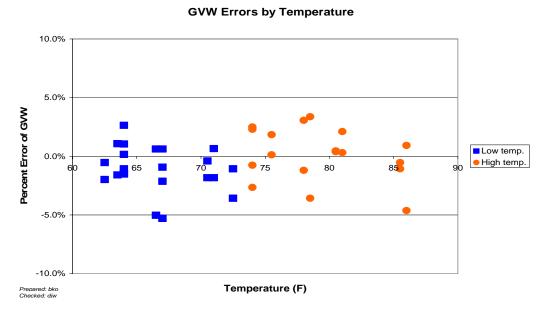


Figure 3-3 Post-Validation GVW Percent Error vs. Temperature – 260100 - 03-Oct-2007

Figure 3-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to

correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Axle spacing errors appear to be consistent throughout the test truck speed range and are limited to maximums of about 0.1 feet. Vehicles speeds appear to have no effect on the error of measured axle spacing.

# Drive Tandem Spacing vs. Radar Speed

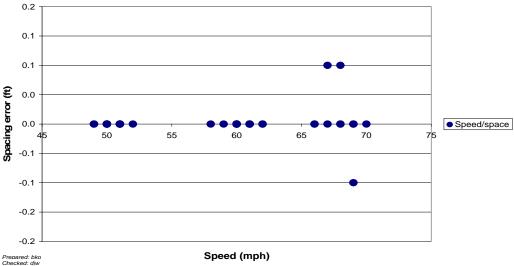


Figure 3-4 Post-Validation Spacing vs. Speed – 260100 – 03-Oct-2007

#### 3.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 62 to 73 degrees Fahrenheit for Low temperature and 74 to 86 degrees Fahrenheit for High temperature.

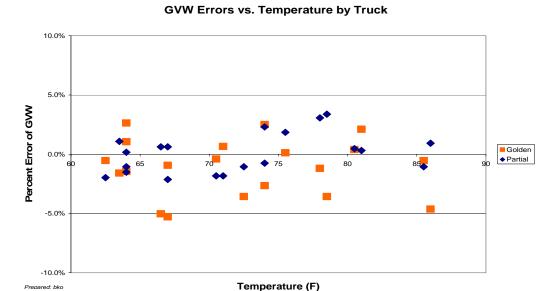
Table 3-2 Post-Validation Results by Temperature Bin – 260100 – 03-Oct-2007

Element	95% Limit	Low Temperature 62 to 73 °F	High Temperature 74 to 86 °F
Steering axles	<u>+</u> 20 %	$5.2 \pm 8.7\%$	$5.8 \pm 5.0\%$
Tandem axles	<u>+</u> 15 %	$-2.1 \pm 5.2\%$	$-0.7 \pm 7.0\%$
GVW	<u>+</u> 10 %	$-1.1 \pm 4.0\%$	$0.2 \pm 4.7\%$
Speed	<u>+</u> 1 mph	$0.5 \pm 1.2 \text{ mph}$	$0.2 \pm 1.2 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-2, it appears that the mean error for steering axles is greater than the mean error for tandem and GVW weights at all temperatures. The equipment appears to estimate GVW and tandem axle weights with reasonable accuracy, with slight underestimation of both at the lower temperatures. The scatter for steering axle error is greater at the lower temperatures, while error scatter for tandem weights is greater at the higher temperatures. Scatter for GVW error appears to be consistent at all temperatures.

Figure 3-5 is the distribution of GVW Errors versus Temperature by Truck graph. The figure illustrates consistent GVW errors for both trucks over the observed temperature range.



# Figure 3-5 Post-Validation GVW Percent Error vs. Temperature by Truck – 260100 – 03-Oct-2007

Figure 3-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Figure 3-6 shows how the WIM equipment overestimates the steering axle weights at all temperatures. Variability of the error is decreasing as the temperature increases. This may be a function of the number of observations rather than an actual temperature effect.



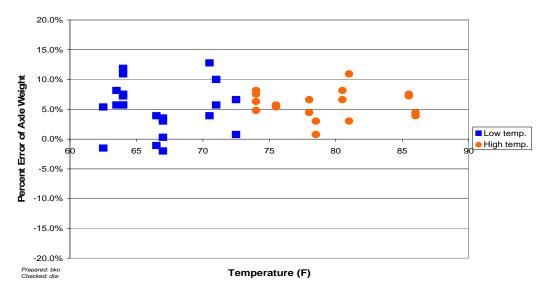


Figure 3-6 Post-Validation Steering Axle Error vs. Temperature by Group – 260100 – 03-Oct-2007

#### 3.2 Speed-based Analysis

The three speed groups were divided using 49 to 55 mph for Low speed, 56 to 62 mph for Medium speed and 63+ mph for High speed.

Table 3-3 Post-Validation Results by Speed Bin – 260100 – 03-Oct-2007

Element	95%	Low	Medium	High
	Limit	Speed	Speed	Speed
		49 to 55 mph	56 to 62 mph	63+ mph
Steering axles	<u>+</u> 20 %	$2.2 \pm 5.8\%$	$7.4 \pm 5.2\%$	$7.1 \pm 5.8\%$
Tandem axles	<u>+</u> 15 %	$-2.4 \pm 7.3\%$	$-1.3 \pm 5.7\%$	$-0.6 \pm 5.3\%$
GVW	<u>+</u> 10 %	$-1.7 \pm 5.5\%$	$-0.1 \pm 3.6\%$	$0.4 \pm 3.4\%$
Speed	<u>+</u> 1 mph	$0.4 \pm 1.1 \text{ mph}$	$0.2 \pm 1.2$ mph	$0.5 \pm 1.5$ mph
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0$ ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 3-3, it appears that the mean error for steering axle weights is generally greater than the mean error for tandem axle weights and GVW at all speeds. For steering axle weights, the equipment overestimates at all speeds, with greater overestimation at the medium and high speeds. Scatter for steering axle weights appears to be consistent throughout the entire speed range. Tandem and GVW weights are generally underestimated, with scatter of the error greater at the lower speeds than the medium and high speeds.

Figure 3-7 illustrates the tendency of the WIM equipment to underestimate GVW for the Golden truck (squares) at the lower speeds, and report fairly consistent GVW weights for

the Partial truck (diamonds) at all speeds. The underestimation of GVW for the Golden truck creates a greater scatter in error at the lower speeds for the truck population as a whole. Individually the scatter in errors for the two trucks at the lower speed appears similar. This subset of speed data is collected below the 15<sup>th</sup> percentile speed for trucks.

**GVW Errors vs. Speed** 

# 10.0% 5.0% -5.0% -5.0% -5.0% Speed (mph)

# Figure 3-7 Post-Validation GVW Percent Error vs. Speed by Truck-260100-03-0ct-2007

Figure 3-8 shows the relationship between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for autocalibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles.

Figure 3-8 shows how the WIM equipment generally overestimates the steering axle weights, with greater overestimation at the medium and high speeds. Variability of the error is generally constant throughout the entire speed range.

#### Steering Axle Errors vs. Speed

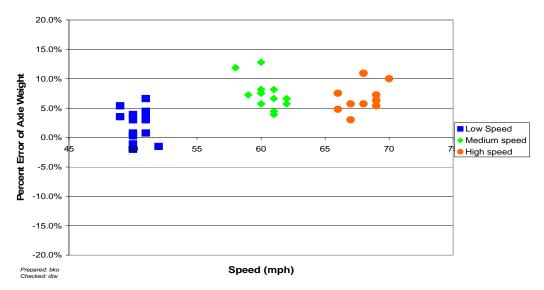


Figure 3-8 Post-Validation Steering Axle Percent Error vs. Speed by Group – 260100 – 03-Oct-2007

#### 3.3 Classification Validation

The agency uses a variant of the FHWA 13-bin classification scheme. Classification 15 has been added to record the number of unclassified vehicles. The classification scheme is known to have difficulties in differentiating between some Class 10s and 13s and in identifying school buses.

The agency has elected not to make additional modifications to its classification scheme to address these issues as there is no unique non-visual way to improve the scheme for the problem vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are 0 percent unknown vehicles and 0 percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications.

Table 3-4 has the classification error rates by class. The overall misclassification rate is 6.8%.

Table 3-4 Truck Misclassification Percentages for 260100 – 03-Oct-2007

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	50	5	4.2	6	14.3
7	N/A				
8	0	9	1.9	10	25
11	N/A	12	N/A	13	16.7

Prepared: djw Checked: bko

The misclassification percentage is computed as the probability that a pair containing the Class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 3-5 Truck Classification Mean Differences for 260100 – 03-Oct-2007

Class	Mean Difference	Class	Mean Difference	Class	Mean Difference
4	-50	5	4	6	- 14
7	N/A				
8	0	9	2	10	- 25
11	N/A	12	N/A	13	20

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen by the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

The error in Class 9 vehicles is the result of a pickup and trailer combination that is visually a Class 5 (single unit vehicle with light trailer) having the correct dimensions and apparently sufficient weight to be considered a Class 9. The Class 10 error is a single vehicle that was identified as a Class 13. The Class 4 errors are school buses identified as Class 5s.

#### 3.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would have met the conditions for

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a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 3-6 Results of Validation Using ASTM E-1318-02 Criteria

Characteristic	Limits for Allowable Error	Percent within Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	100%	Pass
GVW	± 10%	100%	Pass

Prepared: djw Checked: bko

#### **4 Pavement Discussion**

The pavement condition did not appear to influence truck movement across the sensors.

#### 4.1 Profile Analysis

Although there has been no profile data collected in the year prior to this validation profile data was collected within a year of the previous validation. When new profile data becomes available a profile analysis will be done and an amended report submitted.

The WIM site is a section of pavement that is 305 meters long with the WIM scale located at 274.5 meters from the beginning of the test section. An ICC profiler was used to collect longitudinal profiles of the test section with a sampling interval of 25 millimeters.

Profile data collected at the SPS WIM location by Stantec Consultants on June 2, 2006 were processed through the LTPP SPS WIM Index software, version 1.1. While the profile files indicate that this WIM scale is installed on a flexible pavement, a review of the photos and on-site confirmation show that the pavement type around on this section is rigid.

A total of 11 profiler passes were conducted over the WIM site. Since the issuance of the LTPP directive on collection of longitudinal profile data for SPS WIM sections, the requirements have been a minimum of 3 passes in the center of the lane and one shifted to each side. For this site the RSC has completed 5 passes at the center of the lane, 3 passes shifted to the left side of the lane, and 3 passes shifted to the right side of the lane. Shifts to the sides of the lanes were made such that data were collected as close to the lane edges as was safely possible. For each profiler pass, profiles were recorded under the left wheel path (LWP) and the right wheel path (RWP).

The SPS WIM Index software, version 1.0 was developed with four different indices: LRI, SRI, Peak LRI and Peak SRI. The LRI incorporates the pavement profile starting 25.8 m prior to the scale and ending 3.2 m after the scale in the direction of travel. The SRI incorporates a shorter section of pavement profile beginning 2.74 m prior to the WIM scale and ending 0.46 m after the scale. The LRI and SRI are the index values for the actual location of the WIM scale. Peak LRI is the highest value of LRI, within 30 m prior to the scale. Peak SRI indicates the highest value of SRI that is located between

2.45 m prior to the scale and 1.5 m after the scale. Also, a range for each of the indices was developed to provide the smoothness criteria. The ranges are shown in Table 4-1. When all of the values are below the lower thresholds, it is presumed unlikely that pavement smoothness will significantly influence sensor output. When one or more values exceed an upper threshold there is a reasonable expectation that the pavement smoothness will influence the outcome of the validation. When all values are below the upper threshold but not all below the lower threshold, the pavement smoothness may or may not influence the validation outcome.

Table 4-1 Thresholds for WIM Index Values

Index	Lower Threshold (m/km)	Upper Threshold (m/km)
LRI	0.50	2.1
SRI	0.50	2.1
Peak LRI	0.50	2.1
Peak SRI	0.75	2.9

Prepared: djw Checked: bko

Table 4-2 shows the computed index values for all 11 profiler passes for this WIM site. The average values over the passes in each path were also calculated when three or more passes were completed. These are shown in the right most column of the table. Values above the upper index limits are presented in bold while values below the lower index limits are presented in italics.

From Table 4-2 it can be seen that most of the indices computed from the profiles are between the upper and lower threshold values. These results indicate that the pavement smoothness may or may not influence the sensor output. However, since the validation of the equipment was successful, no pavement remediation is recommended at this time.

Table 4-2 WIM Index Values - 260100 -02-Jun-2006

Profiler	Profiler Passes		Pass 1	Pass 2	Pass 3	Pass 4	Pass 5	Ave.
		LRI (m/km)	0.544	0.562	0.600	0.582	0.565	0.571
	LWP	SRI (m/km)	0.630	0.482	0.635	0.648	0.594	0.598
	LWF	Peak LRI (m/km)	0.686	0.744	0.791	0.741	0.752	0.743
Contor		Peak SRI (m/km)	0.674	0.639	0.691	0.658	0.647	0.662
Center		LRI (m/km)	0.809	0.741	0.771	0.805	0.820	0.789
	RWP	SRI (m/km)	1.123	0.973	1.226	1.286	1.316	1.185
	KWF	Peak LRI (m/km)	0.895	0.871	0.946	0.954	0.916	0.916
		Peak SRI (m/km)	1.180	1.112	1.311	1.367	1.363	1.267
Left		LRI (m/km)	0.612	0.578	0.597			0.596
Shift	LWP	SRI (m/km)	0.554	0.538	0.619			0.570
	LWF	Peak LRI (m/km)	0.672	0.640	0.727			0.680
		Peak SRI (m/km)	0.789	0.791	0.689			0.756
	RWP	LRI (m/km)	0.771	0.761	0.795			0.776
		SRI (m/km)	1.044	0.959	1.360			1.121
		Peak LRI (m/km)	1.182	1.196	0.957			1.112

Profiler	Passes		Pass 1	Pass 2	Pass 3	Pass 4	Pass 5	Ave.
		Peak SRI (m/km)	1.295	1.301	1.507			1.368
		LRI (m/km)	0.672	0.682	0.612			0.655
	LWP	SRI (m/km)	0.839	0.824	0.617			0.760
	LWF	Peak LRI (m/km)	0.807	0.916	0.853			0.859
Right		Peak SRI (m/km)	0.911	0.951	0.713			0.858
Shift		LRI (m/km)	0.854	0.903	0.779			0.845
	RWP	SRI (m/km)	1.217	1.305	1.266			1.263
	RWP	Peak LRI (m/km)	0.977	1.009	0.937			0.974
		Peak SRI (m/km)	1.313	1.379	1.285			1.326

Prepared: djw Checked: bko

#### 4.2 Distress Survey and Any Applicable Photos

During a visual survey of the pavement, no distresses that would influence truck movement across the WIM scales were noted.

A lateral crack in the area of the trailing WIM sensor appears to have diminished the lead-in cable's insulation resistance properties. This is shown in Figure 4-1



**Figure 4-1 Trailing Sensor Crack – 260100 – 02-Oct-2007** 

#### 4.3 Vehicle-pavement Interaction Discussion

A visual observation of the trucks as they approach, traverse and leave the sensor area did not indicate any visible motion of the trucks that would affect the performance of the WIM scales. Trucks appear to track down the wheel path and daylight cannot be seen between the tires of any of the sensors for the equipment.

## **5 Equipment Discussion**

The traffic monitoring equipment at this location includes quartz piezo sensors and DAW 190. These sensors are installed ten feet apart in a staggered configuration in a portland cement concrete pavement.

There were no changes in basic equipment operating condition since the validation on July 11, 2006.

#### 5.1 Pre-Evaluation Diagnostics

A complete electronic and electrical check of all system components including in-road sensors, electrical power, and telephone service were performed immediately prior to the evaluation. Although it appears to be working normally, insulation resistance measurements of the trailing WIM sensor indicated that it is operating outside of the manufacturer's minimum standard for insulation resistance. All other sensors and system components were found to be within operating parameters.

#### 5.2 Calibration Process

The equipment required one-iteration of the calibration process between the initial 40 runs and the final 40 runs.

#### 5.2.1 Calibration Iteration 1

For this equipment, there are 4 primary calibration factors. The overall sensitivity factor is increased to account for underestimation of all weights at all speeds and is decreased to compensate for overestimation of all weights at all speeds.

The three speed point factors are increased or decreased to compensate for underestimation or overestimation of weights at the lower, medium and high speed ranges.

For this site, the starting factors were:

Overall sensitivity: 820

Speed compensation factor 1: 1000 Speed compensation factor 2: 1014 Speed compensation factor 3: 1044

The results of the pre-validation test runs indicated that the equipment was generally underestimating all weights by approximately 10%, with additional underestimation at the medium and high speeds of approximately 3% and 2% respectively.

As a result, the primary factors were adjusted to compensate for these underestimations and the following factors were installed:

Overall sensitivity: 900

Speed compensation factor 1: 1000 Speed compensation factor 2: 1050

#### Speed compensation factor 3: 1071

The agency made the same calculations and selected the new factors which they input into the controller.

The results of the 12 calibration verification runs are shown in Table 5-1. No further calibrations were deemed necessary. A final 28 test runs were conducted to complete the post-validation series of 40 runs.

**Table 5-1 Calibration Iteration 1 Results – 260100 – 03-Oct-2007 (09:09 AM)** 

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$4.2 \pm 8.7\%$	Pass
Tandem axles	±15 percent	$-1.8 \pm 5.5\%$	Pass
GVW	±10 percent	$-1.0 \pm 4.3\%$	Pass
Speed	<u>+</u> 1 mph	0.6 ± 1.1 mph	Fail
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

#### **GVW Errors by Speed Group**

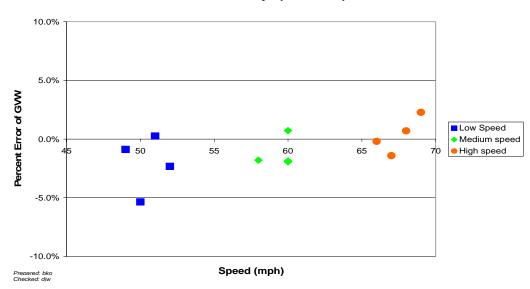


Figure 5-1 Calibration Iteration 1 GVW Percent Error vs. Speed Group – 260100 – 03-Oct-2007 (09:09 AM)

#### 5.3 Summary of Traffic Sheet 16s

This site has validation information from previous visits as well as the current one in the tables below.

Table 5-2 has the information for TRF\_CALIBRATION\_AVC for Sheet 16s submitted prior to this validation as well as the information for the current visit.

**Table 5-2 Classification Validation History – 260100 – 03-Oct-2007** 

Date	Method	Mean Difference				Percent
		Class 9	Class 8	Class 13	Other 2	Unclassified
10/03/2007	Manual	2.0	0.0	20.0		0.0
10/02/2007	Manual	0.0	0.0	100.0		0.0
07/11/2006	Manual	0.0	0.0	0.0		0.0
12/07/2005	Manual	0.0	0.0			0.0
12/06/2005	Manual	0.0	0.0			0.0

Prepared: djw Checked: bko

Table 5-3 has the information for TRF\_CALIBRATION\_WIM for Sheet 16s submitted prior to this validation as well as the information for the current visit.

Table 5-3 Weight Validation History – 260100 – 03-Oct-2007

Date	Method	Mean Error and (SD)			
		GVW	Single Axles	Tandem Axles	
10/03/2007	Test Trucks	-0.5 (2.1)	5.5 (3.5)	-1.5 (3.1)	
10/02/2007	Test Trucks	-10.8 (2.1)	-7.3 (3.1)	-11.4 (3.4)	
07/11/2006	Test Trucks	-0.6 (1.7)	0.5 (4.7)	-1.2 (2.1)	
12/08/2005	Test Trucks	-2.1 (3.4)	-4.2 (4.0)	-1.7 (4.3)	
12/07/2005	Test Trucks	19.8 (7.6)	19.6 (3.6)	19.7 (9.7)	

Prepared: djw Che

Checked: bko

Differences in temperature ranges during separate validations typically result in increased weight errors. At this site, the weight errors increased 10% from the validation on 11 July even though temperatures were very similar for these two validations. The shift in reported weights by this equipment may be related to degradation of the trailing WIM sensor operation described in Section 5.1.

#### 5.4 Projected Maintenance/Replacement Requirements

Due to the diminished resistive properties of the trailing WIM sensor's lead-in cable, the sensor needs to be replaced.

# 6 Pre-Validation Analysis

This pre-validation analysis is based on test runs conducted Oct 2, 2007 during the morning and early afternoon hours at test site 260100 on US Route 27. This SPS-1 site is installed on the southbound, righthand lane of a four-lane divided facility. No auto-calibration was used during test runs. The two trucks used for initial validation included:

- 1. 5-axle tractor semi-trailer combination with a tractor having an air suspension and trailer with standard rear tandem and an air suspension loaded to 75,510 lbs
- 2. 5-axle tractor semi-trailer with a tractor having an air suspension and a trailer with a standard rear tandem and an air suspension loaded to 64,820 lbs., the partial truck.

For the initial validation, each truck made a total of 20 passes over the WIM scale at speeds ranging from approximately 49 to 68 miles per hour. The desired speed range was achieved during this validation. Pavement surface temperatures were recorded during the test runs ranging from about 63 to 97 degrees Fahrenheit. The desired 30 degree Fahrenheit temperature range was also achieved. The computed values of 95% confidence limits of each statistic for the total population are in Table 6-1.

As shown in Table 6-1, the site did not meet LTPP performance criteria for research quality data for GVW or Tandem axle weight or speed.

**Table 6-1 Pre-Validation Results – 260100 – 02-Oct-2007** 

SPS-1, -2, -5, -6 and -8	95 %Confidence	Site Values	Pass/Fail
	Limit of Error		
Steering axles	±20 percent	$-7.3 \pm 6.2\%$	Pass
Tandem axles	<u>+</u> 15 percent	$-11.4 \pm 6.7\%$	Fail
GVW	<u>+</u> 10 percent	$-10.8 \pm 4.3\%$	Fail
Speed	<u>+</u> 1 mph [2 km/hr]	$0.1 \pm 1.5 \text{ mph}$	Fail
Axle spacing	<u>+</u> 0.5 ft [150mm]	$0.0 \pm 0.1 \text{ ft}$	Pass

Prepared: djw Checked: bko

The test runs were conducted primarily during the morning and early afternoon hours under cloudy weather conditions, resulting in a limited range of pavement temperatures. The runs were also conducted at various speeds to determine the effects of these variables on the performance of the WIM scale. To investigate these effects, the dataset was split into three speed groups and two temperature groups. The distribution of runs within these groupings is illustrated in Figure 6-1. The figure indicates that the desired distribution of speed and temperature combinations was achieved for this set of validation runs. There were insufficient data points in the upper end of the range to justify splitting the data into three groups. A third group would have had less than the minimum eight points considered necessary for this project.

The three speed groups were divided into 49 to 55 mph for Low speed, 56 to 62 mph for Medium speed and 63+ mph for High speed. The two temperature groups were created by splitting the runs between those at 63 to 75 degrees Fahrenheit for Low temperature and 76 to 97 degrees Fahrenheit for High temperature.

#### **Speed versus Temperature Combinations**

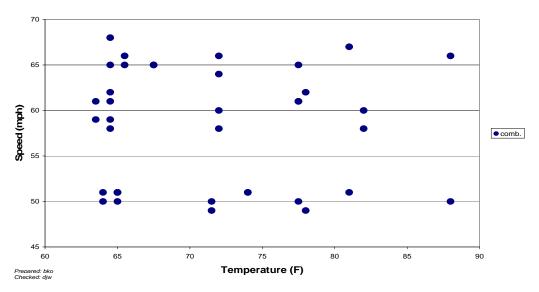


Figure 6-1 Pre-Validation Speed-Temperature Distribution – 260100 – 02-Oct-2007

A series of graphs was developed to investigate visually for any sign of any relationship between speed or temperature and the scale performance.

Figure 6-2 shows the GVW Percent Error vs. Speed graph for the population as a whole. From the figure, it can be seen that the equipment underestimates GVW at all speeds. The scatter of the percent error appears to be consistent over the entire speed range.

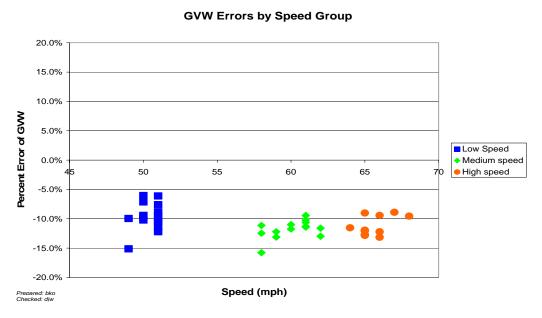


Figure 6-2 Pre-validation GVW Percent Error vs. Speed – 260100 – 02-Oct-2007

Figure 6-3 shows the relationship between temperature and GVW percentage error. The graph illustrates that there does not appear to be a relationship between GVW error and pavement temperature in the observed range.

#### **GVW Errors by Temperature** 20.0% 15.0% 10.0% Percent Error of GVW 5.0% Low temp. 0.0% High temp. 65 70 75 80 85 -5.0% -10.0% -15.0% -20.0%

Figure 6-3 Pre-Validation GVW Percent Error vs. Temperature – 260100 – 02-Oct-2007

Temperature (F)

Figure 6-4 shows the relationship between the drive tandem spacing errors in feet and speeds. This graph is used as a potential indicator of classification errors due to failure to correctly identify spacings on a vehicle. Since the most common reference value is the drive tandem on a Class 9 vehicle, this is the spacing evaluated and plotted for validations. Axle spacing errors appear to be consistent throughout the test truck speed range and are limited to maximums of about 0.1 feet.

#### **Drive Tandem Spacing vs. Radar Speed**

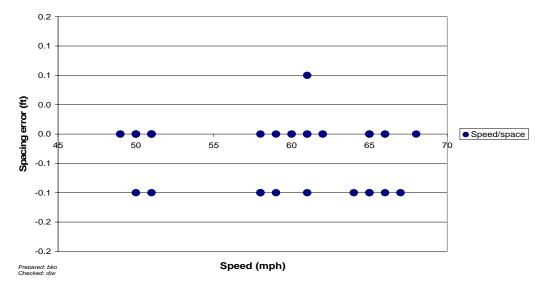


Figure 6-4 Pre-Validation Spacing vs. Speed - 260100 – 02-Oct-2007

#### 6.1 Temperature-based Analysis

The two temperature groups were created by splitting the runs between those at 63 to 75 degrees Fahrenheit for Low temperature and 76 to 97 degrees Fahrenheit for High temperature. There were insufficient data points at the high end of the range to support dividing the data by temperature into three sets covering approximately the same number of degrees and similar numbers of data points.

Table 6-2 Pre-Validation Results by Temperature Bin – 260100 – 02-Oct-2007

Element	95% Limit	Low Temperature 63 to 75 °F	High Temperature 76 to 97 °F
Steering axles	<u>+</u> 20 %	$-8.3 \pm 6.6\%$	$-5.6 \pm 4.0\%$
Tandem axles	<u>+</u> 15 %	-11.7 ± 6.6%	$-10.9 \pm 7.2\%$
GVW	<u>+</u> 10 %	-11.2 ± 4.1%	$-10.1 \pm 4.8\%$
Speed	<u>+</u> 1 mph	$0.2 \pm 1.7 \text{ mph}$	$0.0 \pm 1.2 \text{ mph}$
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

From Table 6-2, it appears that the equipment significantly underestimates all weights at all temperatures. For GVW, scatter in error appears to be consistent at all temperatures. For steering axle weight error, the scatter is greater at the lower temperatures, while the Tandem weight scatter is greater at the higher temperatures.

Figure 6-5 shows the distribution of GVW Errors versus Temperature by Truck. The figure illustrates the tendency of the WIM equipment to report consistent underestimates of GVW weights for both trucks over the entire temperature range.

Consistency of the scatter over the observed range cannot be addressed due to the limited number of observations at High temperature for this validation.

#### **GVW Errors vs. Temperature by Truck**

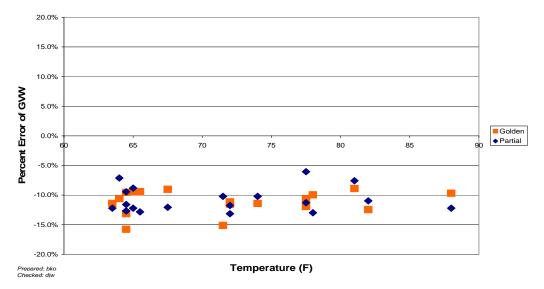


Figure 6-5 Pre-Validation GVW Percent Error vs. Temperature by Truck – 260100 – 02-Oct-2007

Figure 6-6 shows the relationship between steering axle errors and temperature. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for auto-calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Figure 6-6 shows how the WIM equipment generally underestimates the steering axle weights. Variability of the error is greater at the lower temperatures.

#### Steering Axle Errors vs. Temperature

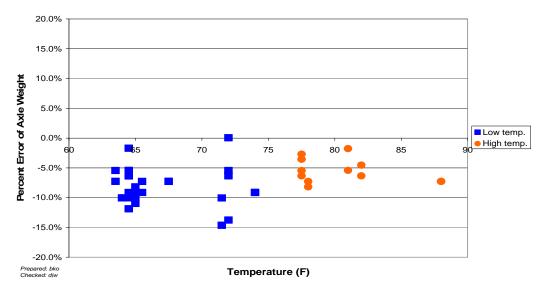


Figure 6-6 Pre-Validation Steering Axle Error vs. Temperature by Group – 260100 – 02-Oct-2007

#### 6.2 Speed-based Analysis

The speed groups were divided as follows: Low speed -49 to 55 mph, Medium speed -56 to 62 mph and High speed -63+ mph.

Table 6-3 Pre-Validation Results by Speed Bin – 260100 – 02-Oct-2007

Element	95%	Low	Medium	High	
	Limit	Speed	Speed	Speed	
		49 to 55 mph	56 to 62 mph	63+ mph	
Steering axles	<u>+</u> 20 %	$-8.9 \pm 4.9\%$	$-6.2 \pm 5.5\%$	$-6.5 \pm 8.6\%$	
Tandem axles	<u>+</u> 15 %	$-9.8 \pm 6.7\%$	$-12.9 \pm 5.9\%$	$-11.7 \pm 6.6\%$	
GVW	<u>+</u> 10 %	$-9.6 \pm 5.1\%$	-11.8 ± 3.3%	$-11.2 \pm 3.7\%$	
Speed	<u>+</u> 1 mph	$0.1 \pm 1.4 \text{ mph}$	$-0.2 \pm 1.5 \text{ mph}$	$0.5 \pm 1.8 \text{ mph}$	
Axle spacing	<u>+</u> 0.5 ft	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$	

Prepared: djw Checked: bko

From Table 6-3, it appears that the mean error for steering axles is less than the mean error for tandem axles and GVW at all speeds. Steering axle underestimation is greater at the lower speeds. Tandem axle weight and GVW underestimations are greater at the medium and high speeds. The scatter for steering axle error is greater at the higher speeds. The scatter for GVW is greater at the lower speeds.

Figure 6-7 illustrates the tendency of the WIM equipment to underestimate GVW for both trucks at all speeds. The variability in error appears to be slightly greater at the lower speeds.

#### **GVW Errors vs. Speed**

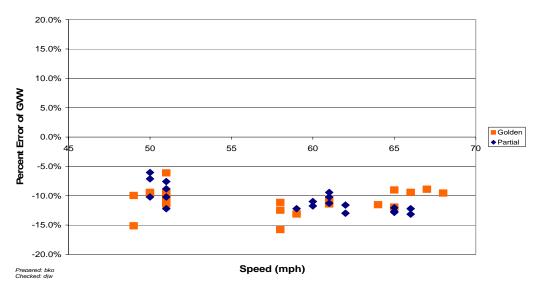


Figure 6-7 Pre-Validation GVW Percent Error vs. Speed Group - 260100 -02-Oct-2007

Figure 6-8 shows the relation between steering axle errors and speed. This graph is included due to the frequent use of steering axle weights of Class 9 vehicles for calibration. This site does not use auto-calibration. The steering axles in this graph are associated only with Class 9 vehicles. Figure 6-8 shows how the WIM equipment generally underestimates the steering axle weights. Variability of the error appears to increase as speed increases.

#### Steering Axle Errors vs. Speed

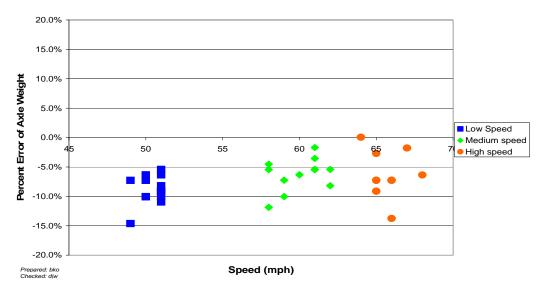


Figure 6-8 Pre-Validation Steering Axle Percent Error vs. Speed Group - 260100 – 02-Oct-2007

#### 6.3 Classification Validation

The agency uses a variant of the FHWA 13-bin classification scheme. Classification 15 has been added to record the number of unclassified vehicles. The classification scheme is known to have difficulties in differentiating between some Class 10s and 13s and in identifying school buses. The agency has elected not to make additional modifications to its classification scheme to address these issues as there is no unique non-visual way to improve the scheme for the problem vehicles.

The classification validation is intended to find gross errors in vehicle classification, not to validate the installed algorithm. A sample of 100 trucks was collected at the site. The classification identification is to identify gross errors in classification, not validate the classification algorithm. Video was taken at the site to provide ground truth for the evaluation. Based on a 100 percent sample it was determined that there are 0 percent unknown vehicles and 1.9 percent unclassified vehicles.

The second check is the ability of the algorithm to correctly distinguish between truck classes with no more than 2% errors in such classifications. Table 6-4 has the classification error rates by class. The overall misclassification rate is 9.8 percent.

Table 6-4 Truck Misclassification Percentages for 260100 – 02-Oct-2007

Class	Percent Error	Class	Percent Error	Class	Percent Error
4	100	5	17	6	0
7	100				
8	0	9	0.0	10	13
11	N/A	12	N/A	13	N/A

Prepared: djw

Checked: bko

The misclassification percentage is computed as the probability that a pair containing the class of interest does NOT include a match. Thus if there are eight pairs of observations with at least one Class 9 and only six of them are matches, the error rate is 25 percent. The percent error and the mean differences reported below do not represent the same statistic. It is possible to have error rates greater than 0 with a mean difference of zero.

Table 6-5 Truck Classification Mean Differences for 260100 – 02-Oct-2007

Class	Mean	Class	Mean	Class	Mean
	Difference		Difference		Difference
4	-100	5	10	6	0
7	-100				
8	0	9	0.0	10	-13
11	N/A	12	N/A	13	N/A

Prepared: djw Checked: bko

These error rates are normalized to represent how many vehicles of the class are expected to be over- or under-counted for every hundred of that class observed by the equipment. Thus a value of 0 means the class is identified correctly on average. A number between -1 and -100 indicates at least that number of vehicles either missed or not assigned to the class by the equipment. It is not possible to miss more than all of them or one hundred out of one hundred. Numbers 1 or larger indicate at least how many more vehicles are assigned to the class than the actual "hundred observed". Classes marked Unknown (UNK) are those identified by the equipment but no vehicles of the type were seen the observer. There is no way to tell how many vehicles of that type might actually exist. N/A means no vehicles of the class were recorded by either the equipment or the observer.

The Class 4 errors are school buses identified as Class 5s. The Class 7 error is a crane that the equipment counted different numbers of axles on each loop. This is the unclassified vehicle. The Class 10 error is a single vehicle.

#### 6.4 Evaluation by ASTM E-1318 Criteria

The ASTM E-1318 criteria for a successful validation of Type I sites is 95% of the observed errors within the limits for allowable errors for each of the relevant statistics. If this site had been evaluated using ASTM E-1318-02 it would not have met the conditions for a Type I site exclusive of wheel loads. LTPP does not validate WIM performance with respect to wheel loads.

Table 6-6 Results of Validation Using ASTM E-1318-02 Criteria

	Limits for Allowable	Percent within	
Characteristic	Error	Allowable Error	Pass/Fail
Single Axles	± 20%	100%	Pass
Axle Groups	± 15%	83.8%	Fail
GVW	± 10%	35%	Fail

Prepared: djw Checked: bko

#### 6.5 Prior Validations

The last validation for this site was done July 11, 2006. It was the second validation of the site. The site was producing research quality data. Figure 6-9 shows the GVW Percent Error vs. Speed for the post validation runs. The site was validated with two trucks. The "Golden" truck was loaded to 77,180 lbs. The "partial" truck, which had air suspension on both tandems, was loaded to 65,340 lbs.

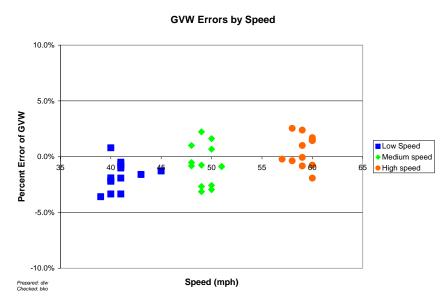


Figure 6-9 Last Validation GVW Percent Error vs. Speed – 260100 – 11-Jul-2006

Table 6-7 shows the overall results from the last validation. The site was slightly underestimating GVW and tandem axle weights. It was overestimating steering axle weights. Single axle weight errors were calculated because the Partial truck had a split tandem on the trailer. The end conditions from the prior validation are similar to those for the end conditions of the current validation.

Table 6-7 Last Validation Final Results – 260100 – 11-Jul-2006

SPS-1, -2, -5, -6 and -8	95 %Confidence Limit of Error	Site Values	Pass/Fail
Steering axles	±20 percent	$3.5 \pm 6.7\%$	Pass
Single axles	±20 percent	$0.5 \pm 9.4\%$	Pass
Tandem axles	±15 percent	-1.2 ± 4.1%	Pass
Gross vehicle weights	±10 percent	$-0.6 \pm 3.5\%$	Pass
Speed	<u>+</u> 1 mph [2 km/hr]	0.3 ± 1.4 mph	Fail
Axle spacing	<u>+</u> 0.5 ft [150 mm]	$0.0 \pm 0.0 \text{ ft}$	Pass

Prepared: djw Checked: bko

Due to the limited range of temperatures during the period of testing, the site could not be evaluated for temperature effects. Only four points were observed at the lower end of the

range (79-90) from the full range of 79 to 96. Through this validation, the equipment has been observed at temperature from 1 to 96 degrees Fahrenheit.

Table 6-8 has the results of the prior post validation by speed groups. The tendency to have decreasing errors with increasing temperatures is observed here. The last validation was conducted with speeds limited by the truck speed limit.

Table 6-8 Last Validation Results by Speed Bin – 260100 – 11-Jul-2006

Element	95% Limit	Low Speed 39 to 45 mph	Medium Speed 46 to 51 mph	High Speed 52+ mph
Steering axles	<u>+</u> 20 %	$2.2 \pm 7.4\%$	$2.8 \pm 4.7\%$	$5.7 \pm 7.1\%$
Single axles	<u>+</u> 20 %	$-1.2 \pm 10.1\%$	$1.0 \pm 7.9\%$	$1.6 \pm 10.3\%$
Tandem axles	<u>+</u> 15 %	$-1.9 \pm 3.5\%$	$-1.6 \pm 4.3\%$	$0.1 \pm 4.1\%$
GVW	<u>+</u> 10 %	$-1.7 \pm 2.7\%$	$-0.7 \pm 3.8\%$	$0.6 \pm 3.0\%$
Speed	<u>+</u> 1 mph	$0.1 \pm 1.9 \text{ mph}$	$0.4 \pm 1.4 \text{ mph}$	$0.0 \pm 0.1 \text{ mph}$
Axle spacing	+ 0.5 ft	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.0 \text{ ft}$	$0.0 \pm 0.1 \text{ ft}$

Prepared: djw Checked: bko

## 7 Data Availability and Quality

As of October 2, 2007 this site does not have at least 5 years of research quality data. Research quality data is defined to be at least 210 days in a year of data of known calibration meeting LTPP's precision requirements.

Data that has validation information available has been reviewed in light of the patterns present in the two weeks immediately following a validation/calibration activity. A determination of research quality data is based on the consistency with the validation pattern. Data that follows consistent and rational patterns in the absence of calibration information may be considered nominally of research quality pending validation information with which to compare it. Data that is inconsistent with expected patterns and has no supporting validation information is not considered research quality.

The amount and coverage for the site is shown in Table 7-1. The value for months is a measure of the seasonal variation in the data. The indicator of coverage indicates whether day of week variation has been accounted for on an annual basis. As can be seen from the table, between 1996 and 2006 all years but 1996, 1998 and 1999 for classification and 1996,1999 and 2002 for weight have a sufficient quantity of data to be considered complete years of data. With only the 2006 validation information available for these years it can be seen that at least four additional years of research quality data are needed to meet the goal of a minimum of 5 years of research weight data. Since the site was installed in June 2005, analysis of data from prior years for consideration as research quality data will require validation information for that installation. With the observed failure condition at the beginning of this validation and the agency's intent not to replace the sensor until Spring 2008, it is unlikely that 2007 will qualify as a year of research quality data.

Table 7-1 Amount of Traffic Data Available 260100 – 02-Oct-2007

Year	Classification	Months	Coverage	Weight	Months	Coverage
	Days			Days		
1996	176	7	Full week	191	7	Full week
1997	339	12	Full week	322	11	Full week
1998	1	1	Weekday(s)	356	12	Full week
1999	127	6	Full week	136	6	Full week
2000	309	11	Full week	309	12	Full week
2001	345	12	Full week	341	12	Full week
2002	345	12	Full week	353	12	Full week
2003	300	10	Full week	298	10	Full week
2004	280	11	Full week	323	11	Full week
2005	333	12	Full week	340	12	Full week
2006	316	12	Full week	357	12	Full week
2007	135	5	Full week	144	5	Full week

Prepared: djw Checked: bko

GVW graphs and characteristics associated with them are used as data screening tools. As a result classes constituting more that ten percent of the truck population are considered major sub-groups whose evaluation characteristics should be identified for use in screening. The typical values to be used for reviewing incoming data after a validation are determined starting with data from the day after the completion of a validation.

Class 5s and Class 9s constitute more than 10 percent of the truck population. Based on the data collected from the end of the last calibration iteration the following are the expected values for these populations. The precise values to be used in data review will need to be determined by the RSC on receipt of the first 14 days of data after the successful validation. For sites that do not meet LTPP precision requirements, this period may still be used as a starting point from which to track scale changes.

Table 7-2 is generated with a column for every vehicle class 4 or higher that represents 10 percent or more of the truck (class 4-20) population. In creating Table 7-2 the following definitions are used:

- o Class 9 overweights are defined as the percentage of vehicles greater than 88,000 pounds
- o Class 9 underweights are defined as the percentage of vehicles less than 20,000 pounds.
- o Class 9 unloaded peak is the bin less than 44,000 pounds with the greatest percentage of trucks.
- o Class 9 loaded peak is the bin 60,000 pounds or larger with the greatest percentage of trucks.
- For all other trucks the typical axle configuration is used to determine the maximum allowable weight based on 18,000 pounds for single axles and 34,000 pounds for tandem axles. A ten percent cushion above that maximum is used to set the overweight threshold.

- For all other trucks in the absence of site specific information the computation of under weights assumes the power unit weighs 10,000 pounds and each axle on a trailer 5,000 pounds. Ninety percent of the total for the unloaded configuration is the value below which a truck is considered under weight.
- o For all trucks other than class 9s that have a bi-modal distribution the unloaded peak is defined to be in a bin less than or equal to half of the allowable maximum weight.
- o For all trucks other than class 9s that have a bi-modal distribution the loaded peak is defined to be in a bin greater than or equal to half of the allowable maximum weight.

There may be more than one bin identified for the unloaded or loaded peak due to the small sample size collected after validation. Where only one peak exists, the peak rather than a loaded or unloaded peak is identified. This may happen with single unit trucks. It is not expected to occur with combination vehicles.

**Table 7-2 GVW Characteristics of Major sub-groups of Trucks – 260100 – 03-Oct-2007** 

Characteristic	Class 5	Class 9	
Percentage Overweights	0.0%	0.7%	
Percentage Underweights	1.3%	0.0%	
Unloaded Peak		36,000 lbs	
Loaded Peak		84,000 lbs	
Peak	12,000 lbs		

Prepared: djw Checked: bko

The expected percentage of unclassified vehicles among the truck population is 7.5%. This is based on the percentage of unclassified vehicles in the post-validation data download.

The graphical screening comparison figures are found in Figure 7-2 through Figure 7-4. These are based on data collected immediately after the validation and may not be wholly representative of the population at the site. They should however provide a sense of the statistics expected when SPS comparison data is computed for the post-validation Sheet 16.



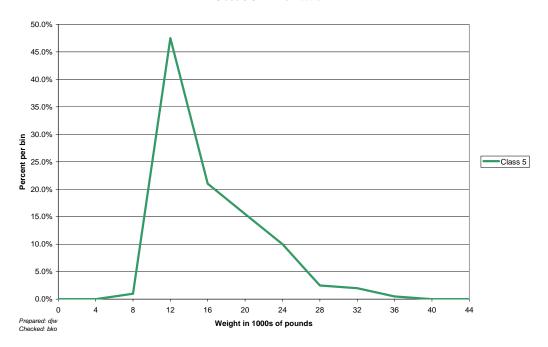


Figure 7-1 Expected GVW Distribution Class 5 – 260100 – 03-Oct-2007

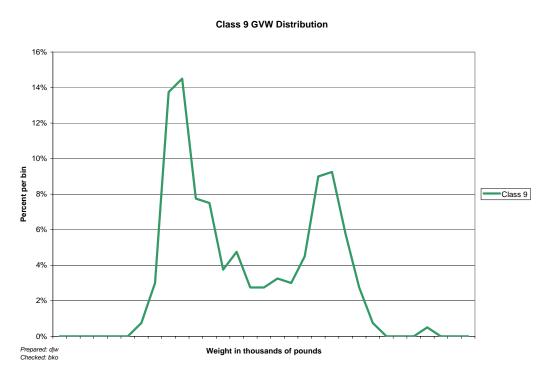


Figure 7-2 Expected GVW Distribution Class 9 – 260100 – 03-Oct-2007

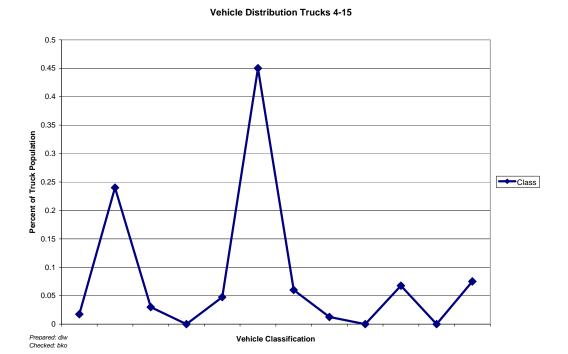


Figure 7-3 Expected Vehicle Distribution – 260100 – 03-Oct-2007

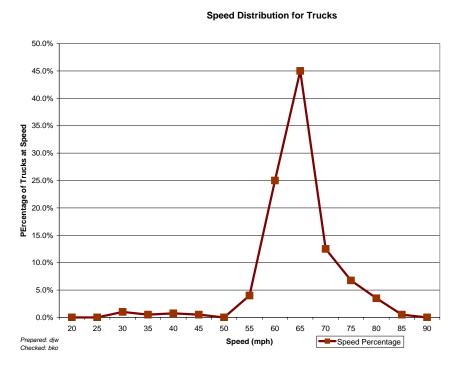


Figure 7-4 Expected Speed Distribution – 260100 – 03-Oct-2007

#### 8 Data Sheets

The following is a listing of data sheets incorporated in Appendix A.

```
Sheet 19 - \text{Truck } 1 - 3\text{S2} loaded air suspension (2 pages)
```

Sheet 19 – Truck 1a – 3S2 loaded air suspension (2 pages)

Sheet 19 – Truck 2 – 3S2 loaded air suspension (3 pages)

```
Sheet 20 – Classification and Speed verification Pre-Validation (2 pages)
```

Sheet 20 – Classification and Speed verification – Post-Validation (2 pages)

```
Sheet 21 – Pre-Validation (3 pages)
```

Sheet 21 – Calibration Iteration 1 – (1 page)

Sheet 21 – Post-Validation (2 pages)

Calibration Iteration 1 Worksheets – (1 page)

Test Truck Photographs (9 pages)

Michigan Classification Scheme (1 page)

Final System Parameters (1 page)

#### 9 Updated Handout Guide and Sheet 17

A copy of the handout has been included following this page. It includes a current Sheet 17 with all applicable maps and photographs. There are no significant changes in the information provided.

# 10 Updated Sheet 18

A current Sheet 18 indicating the contacts, conditions for assessments and evaluations has been attached following the updated handout guide.

## 11 Traffic Sheet 16(s)

Sheet 16s for the pre-validation and post-validation conditions are attached following the current Sheet 18 information at the very end of the report.

# POST-VISIT HANDOUT GUIDE FOR SPS WIM FIELD VALIDATION

# **STATE: Michigan**

# **SHRP ID: 0100**

General Information	. 1
Contact Information	. 1
Agenda	. 1
Site Location/ Directions	
Truck Route Information	. 3
	Agenda

# Figures

Figure 4-1 - Site Location for SPS-1 in Michigan	
Figure 5-1 - Truck Scale Location for Michigan SPS-1	3
Figure 5-2 - Truck Route for SPS-1 in Michigan	
Figure 6-1 - Sketch of equipment layout	
Figure 6-2 - Site Map 260100	8
Photos	
Photo 1 26_0100_Upstream_10_02_07.jpg	9
Photo 2 26_0100_Downstream_10_02_07.jpg	9
Photo 3 26_0100_Power_Service_Box_10_02_07.jpg	10
Photo 4 26_0100_Telephone_Service_Box_10_02_07.jpg	
Photo 5 26_0100_Cabinet_Exterior_10_02_07 011.jpg	
Photo 6 26_0100_Cabinet_Interior_10_02_07.jpg	
Photo 7 26_0100_Leading_WIM_Sensor_10_02_07.jpg	
Photo 8 26_0100_Trailing_WIM_Sensor_10_02_07.jpg	
Photo 9 26_0100_WIM_site_10_02_07.jpg	
Photo 10 26 0100 Loop Sensor 10 02 07.jpg	

Validation – MI 0100 Assessment, Calibration and Performance Evaluation of LTPP SPS Weigh-in-Motion (WIM) Sites MACTEC Ref. 6420070022 2.96 10/15/2007 Page 1 of 15

#### 1. General Information

SITE ID: 260100

LOCATION: US Route 27 South, approximately 2.36 miles north of M-21.

VISIT DATE: October 2, 2007

VISIT TYPE: Validation

#### 2. Contact Information

POINTS OF CONTACT:

Assessment Team Leader: Dean J. Wolf, 301-210-5105, djwolf@mactec.com

**Highway Agency:** Tom Hynes, 517-322-5711, hynest@michigan.gov

James Kramer, 517-322-1716, kramerj2@michigan.gov

FHWA COTR: Debbie Walker, 202-493-3068, deborah.walker@fhwa.dot.gov

FHWA Division Office Liaison: Ryan Rizzo, 517-702-1842, ryan.rizzo@fhwa.dot.gov

LTPP SPS WIM WEB PAGE: http://www.tfhrc.gov/pavement/ltpp/spstraffic/index.htm

#### 3. Agenda

BRIEFING DATE: No briefing requested for this visit

ON SITE PERIOD: October 2, 2007, beginning at 9:00am

TRUCK ROUTE CHECK: Completed. See Figure 5-2.

#### 4. Site Location/ Directions

NEAREST AIRPORT: Capital City Airport, Lansing, MI

DIRECTIONS TO THE SITE: Located on US Route 27, approximately 2.36 miles north of M-21.

MEETING LOCATION: On site beginning at 9:00 a.m.

WIM SITE LOCATION: US 27 South (Latitude: 43.0239° and Longitude: -84.5435°)

## WIM SITE LOCATION MAP:

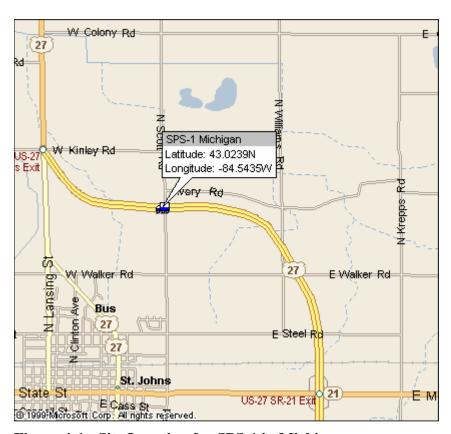


Figure 4-1 - Site Location for SPS-1 in Michigan

#### 5. Truck Route Information

ROUTE RESTRICTIONS: None.

SCALE LOCATION: See Figure 5-1.

Don's Windmill Truck Stop, I-96 Exit 98A & I-69 Exit 70, Dimondale, MI, Phone – (517)646-071, Open 24hrs, \$8.00 per weigh.

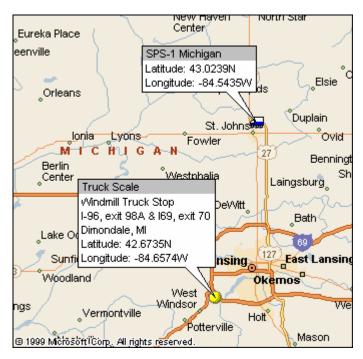


Figure 5-1 - Truck Scale Location for Michigan SPS-1

TRUCK ROUTE: See Figure 5-2.

*Northbound to US-27 Business Exit (W. Kinsley Drive) – 1.0 miles.* 

*Southbound to M-21 Exit – 2.36 miles.* 

 $Total\ distance = 6.72\ miles$  $Total\ time = 10\ minutes$ 

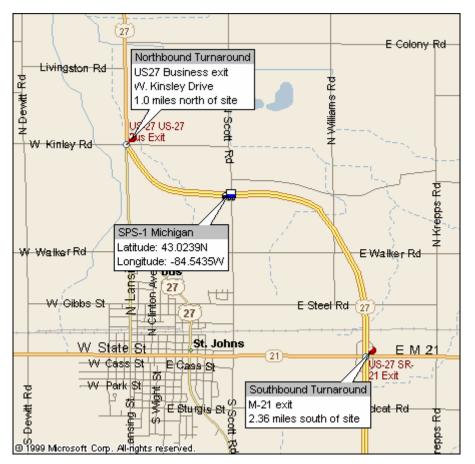


Figure 5-2 - Truck Route for SPS-1 in Michigan

6.	Sheet 17 –	Michigan (26	0100)					
1.*	ROUTE	_US 27	_MILEPOST	_unk_	LTPP DIRI	ECTI	ON - N <u>S</u>	E W
2.*	Nearest	SPS section u	ON - Grade _ pstream of the to nearest upstr	site _	_unknown (	signs	/markings n	ot visible)
3.*		NFIGURATIO n LTPP directi			Lane widt	h _	1_2 ft	
	Median	- 1 – pai 2 – phy 3 – gra 4 – nor	rsical barrier ss		Shoulder -	:	1 – curb and 2 – paved A 3 – paved P 4 – unpaved 5 – none	CC
	Shoulde	er width1_	1 ft					
4.*	PAVEMEN	NT TYPE	_Portland Cond	crete C	ement			
Dar Dar Dar	te <u>10/2/20</u> te <u>10/2/20</u> te <u></u> * SENSOR S	007 Photo 007 Photo SEQUENCE	CONDITION Filename20 Filename20Distress Ph quartz piezo	6 <u>0100</u> 6 <u>0100</u> oto Fil	) Upstream ) Downstreename	_10_( am_1	0_02_07.jp	g
7. *	REPLACE	EMENT AND/	OR GRINDIN OR GRINDIN OR GRINDIN	G	/	/_		
8. I	Intersec distance Intersec distance	eetion/driveway	MONS within 300 m within 300 m ased for turns of	downs	tream of sen			<u>N</u>
9.	DRAINAG	E (Bending pl	ate and load ce	ell syste	ems only)		1 – Open to 2 – Pipe to 6 3 – None	-
	Clearan Clearan	ce under plate ce/access to fl	ush fines from	_ in under	system Y / ]	N		

# 10. \* CABINET LOCATION Same side of road as LTPP lane $\underline{Y} / N$ Median $\underline{Y} / \underline{N}$ Behind barrier $\underline{Y} / \underline{N}$ Distance from edge of traveled lane \_5\_1\_\_ ft Distance from system \_\_4\_7\_ \_\_ ft TYPE \_\_\_\_M\_\_\_ CABINET ACCESS controlled by LTPP / STATE / JOINT ? Contact - name and phone number \_\_\_\_\_Jim Kramer 517-322-1736\_\_\_ Alternate - name and phone number \_\_\_\_\_Bob Brenner 517-322-1673\_\_\_\_\_ 11. \* POWER Distance to cabinet from drop \_\_\_1\_6\_5 \_\_\_ ft Overhead / underground / solar / AC in cabinet? Service provider \_\_\_\_\_ Phone number \_\_\_\_\_ 12. \* TELEPHONE Distance to cabinet from drop \_\_\_1\_6\_5\_\_ ft Overhead / under ground / cell? Service provider \_\_Verizon\_\_\_\_ Phone Number \_\_\_\_\_ 13.\* SYSTEM (software & version no.)- \_\_\_\_DAW-190\_\_\_ Computer connection – RS232 / Parallel port / USB / Other \_\_\_\_\_ 15. PHOTOS **FILENAME** 26 0100 Power Service Box 10 02 07.jpg Power source 26\_0100\_Telephone\_Service\_Box\_10\_02\_07.jpg\_\_\_\_\_ Phone source 26\_0100\_Cabinet Exterior\_10\_02\_07.jpg Cabinet exterior 26 0100\_Cabinet Interior\_10\_02\_07.jpg\_ Cabinet interior Weight sensors 26 0100 Leading WIM Sensor 10 02 07.jpg 26 0100 Trailing WIM Sensor 10 02 07.jpg 26 0100 Loop Sensor 10 02 07.jpg Other sensors Description \_\_\_Loops\_\_ Downstream direction at sensors on LTPP lane \_\_26\_0100\_Downstream\_10\_02\_07.jpg \_\_\_\_\_ Upstream direction at sensors on LTPP lane <u>26 0100 Upstream 10 02 07.jpg</u>

COMMENTS
GPS Coordinates: Latitude: 43.029 <sup>0</sup> and Longitude: -84.5435 <sup>0</sup>
Amenities in St. John's – gas, food, Wal-Mart – located south 2 miles off of M-21 exit, right approximately 2 miles
Hotels in Dewitt, approximately 17 miles from site.
COMPLETED BYDean J. Wolf
PHONE _301-210-5105 DATE COMPLETED9_/_2_4_/_2_0_0_7_

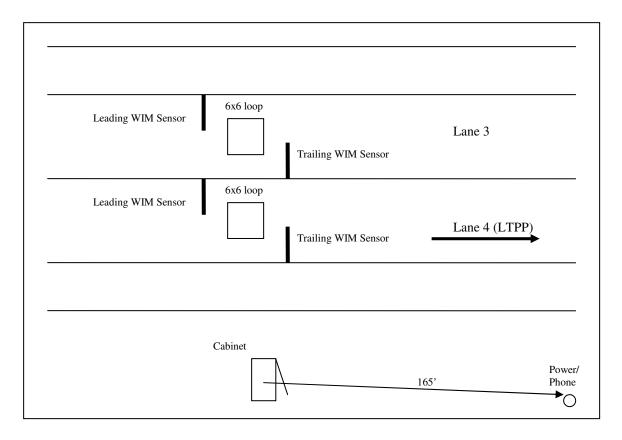


Figure 6-1 - Sketch of equipment layout

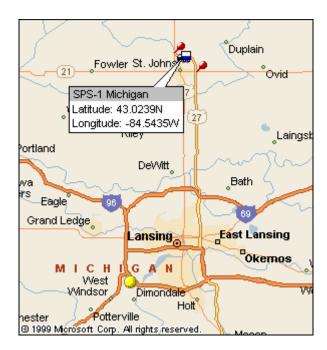


Figure 6-2 - Site Map 260100



Photo 1 26\_0100\_Upstream\_10\_02\_07.jpg



Photo 2 26\_0100\_Downstream\_10\_02\_07.jpg



Photo 3 26\_0100\_Power\_Service\_Box\_10\_02\_07.jpg

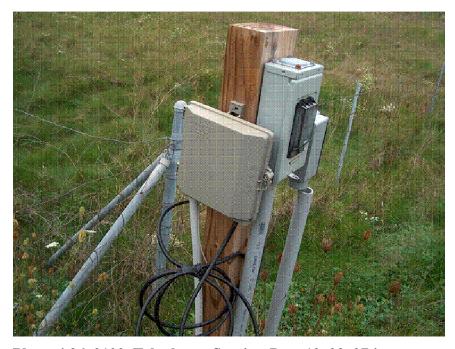


Photo 4 26\_0100\_Telephone\_Service\_Box\_10\_02\_07.jpg



Photo 5 26\_0100\_Cabinet\_Exterior\_10\_02\_07 011.jpg



Photo 6 26\_0100\_Cabinet\_Interior\_10\_02\_07.jpg



Photo 7 26\_0100\_Leading\_WIM\_Sensor\_10\_02\_07.jpg



Photo 8 26\_0100\_Trailing\_WIM\_Sensor\_10\_02\_07.jpg



Photo 9 26\_0100\_WIM\_site\_10\_02\_07.jpg



Photo 10 26\_0100\_Loop\_Sensor\_10\_02\_07.jpg

SHEET 18	STATE CODE	[_2_6_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0_ ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_0_/_0_3_/_2_0_0_7_

1.		ATA PROCESSING –  Down load –  X State only  LTPP read only  LTPP download  LTPP download and copy to state
	b.	Data Review −  □ State per LTPP guidelines  X State − X Weekly □ Twice a Month □ Monthly □ Quarterly □ LTPP
	c.	$\begin{array}{c} Data\ submission - \\ X\ State - \ \square\ Weekly\ \square\ Twice\ a\ month\ X\ Monthly\ \square\ Quarterly \\ \ \square\ LTPP \end{array}$
2.	EC	QUIPMENT –
<b>~</b> .		Purchase –  X State  LTPP
	b.	Installation −  □ Included with purchase  □ Separate contract by State  X State personnel  □ LTPP contract
	c.	Maintenance –  □ Contract with purchase – Expiration Date □ Separate contract LTPP – Expiration Date □ Separate contract State – Expiration Date X State personnel
	d.	Calibration −  □ Vendor  □ State  X LTPP
	e.	Manuals and software control –  X State  □ LTPP
	f.	Power −  i. Type −  □ Overhead  X State  X Underground  □ Solar  □ N/A

SHEET 18	STATE CODE	[_2_6_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0_ ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_0_/_0_3_/_2_0_0_7_

	g.	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
3.		AVEMENT –
	a.	Type – X Portland Concrete Cement  □ Asphalt Concrete
	b.	Allowable rehabilitation activities –  □ Always new □ Replacement as needed □ Grinding and maintenance as needed X Maintenance only □ No remediation
	c.	Profiling Site Markings −  □ Permanent  X Temporary
4.	ON a.	N SITE ACTIVITIES – WIM Validation Check - advance notice required2 □ days X weeks
	b.	Notice for straightedge and grinding check2 □ days X weeks i. On site lead – X State □ LTPP
		<ul><li>ii. Accept grinding –</li><li>X State</li><li>□ LTPP</li></ul>
	c.	Authorization to calibrate site −  □ State only X LTPP
	d.	Calibration Routine –  X LTPP – X Semi-annually □ Annually  □ State per LTPP protocol – □ Semi-annually □ Annually  □ State other –

SHEET 18	STATE CODE	[_2_6_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0_ ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_0_/_0_3_/_2_0_0_7_

5.

6.

e.	Test V	Vehicles Trucks –		
	1.	1st – Air suspension 3S2	☐ State	X LTPP
		2nd –3S2	□ State	X LTPP
		3rd –	$\square$ State	$\Box$ LTPP
		4th –	☐ State	$\Box$ LTPP
	ii.	Loads –	☐ State	X LTPP
	iii.	Drivers –	$\square$ State	X LTPP
f.	Contra	actor(s) with prior successful expe	erience in	WIM calibration in state:
g.	Acces	s to cabinet		
	i.	Personnel Access –		
		X State only		
		☐ Joint ☐ LTPP		
	ii.	Physical Access –		
	111.	X Key		
		☐ Combination		
h.	State 1	personnel required on site –	X Yes	No
i.	Traffi	c Control Required –	$\Box$ Yes X	I No
j.	Enfor	cement Coordination Required –	$\Box$ Yes X	Z No
SI	ΓE SPE	ECIFIC CONDITIONS –		
a.	Funds	and accountability –		
b.	Repor	rts		
c.	Other			
d.	Specia	al Conditions –		
CC	ONTAC	CTS –		
a.	Equip	ment (operational status, access, e	tc.) –	
		Name:Jim Kramer	P	hone: _517-322-1736
		Agency:Michigan	DOT	

SHEET 18	STATE CODE	[_2_6_]
LTPP MONITORED TRAFFIC DATA	SPS PROJECT ID	[ _0_1_0_0_ ]
WIM SITE COORDINATION	DATE: (mm/dd/yyyy)	_1_0_/_0_3_/_2_0_0_7_

b.	Maintenance (equipment) –
	Name:Jim Kramer Phone: _517-322-1736
	Agency:Michigan DOT
c.	Data Processing and Pre-Visit Data –
	Name:Jim Kramer Phone: _517-322-1736
	Agency:Michigan DOT
d.	Construction schedule and verification –
	Name: Phone:
	Agency:
e.	Test Vehicles (trucks, loads, drivers) –
	Name:Brian Hitchcock Phone: _517-521-2124
	Agency:MBH Trucking LLC
f.	Traffic Control –
	Name: Phone:
	Agency:
g.	Enforcement Coordination –
	Name: Phone:
	Agency:
h.	Nearest Static Scale
	Name: _Don's Windmill Truck Stop _ Location: _I-96 Exit 98A, I-69 Exit 70_
	Phone:517-646-6752

## SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[317]
*STATE CODE	[ 26]
*SHRP SECTION ID	[ 0100]

## SITE CALIBRATION INFORMATION

1. * D	DATE OF CALIBRATION (MONTH/DAY/YEAR) [ 10/2/2007]
2. * T	YPE OF EQUIPMENT CALIBRATED WIM CLASSIFIERX BOTH
	EASON FOR CALIBRATION  REGULARLY SCHEDULED SITE VISIT  EQUIPMENT REPLACEMENT  DATA TRIGGERED SYSTEM REVISION  OTHER (SPECIFY) LTPP Validation  RESEARCH  TRAINING  NEW EQUIPMENT INSTALLATION
	ENSORS INSTALLED IN LTPP LANE AT THIS SITE (CHECK ALL THAT APPLY): BARE ROUND PIEZO CERAMICBARE FLAT PIEZOBENDING PLATESCHANNELIZED ROUND PIEZOLOAD CELLSX_QUARTZ PIEZOCHANNELIZED FLAT PIEZOX_INDUCTANCE LOOPSCAPACITANCE PADSOTHER (SPECIFY)
5. EQ	UIPMENT MANUFACTURER IRD/ PAT Traffic
	WIM SYSTEM CALIBRATION SPECIFICS**
6.**CA	LIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N) _X_ TEST TRUCKS
	NUMBER OF TRUCKS COMPARED 2 NUMBER OF TEST TRUCKS USED
	20 PASSES PER TRUCK           TRUCK         TYPE         SUSPENSION           1         9         1           SUSPENSION:         1 - AIR; 2 - LEAF SPRING         2         9         1           3 - OTHER (DESCRIBE)         3
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED AS A PERCENT)  MEAN DIFFERENCE BETWEEN  DYNAMIC AND STATIC GVW10.8 STANDARD DEVIATION2.1  DYNAMIC AND STATIC SINGLE AXLES7.3 STANDARD DEVIATION3.1  DYNAMIC AND STATIC DOUBLE AXLES11.4 STANDARD DEVIATION3.4
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATION WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)506070
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW SPEED)1044
11.**	IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) N IF YES, LIST AND DEFINE AUTO-CALIBRATION VALUE:
	CLASSIFIER TEST SPECIFICS***
12.***	METHOD FOR COLLECTING INDEPENDENT VOLUME MEASUREMENT BY VEHICLE CLASS: VIDEOX_ MANUAL PARALLEL CLASSIFIERS
13.	METHOD TO DETERMINE LENGTH OF COUNT TIMEX NUMBER OF TRUCKS
14.	MEAN DIFFERENCE IN VOLUMES BY VEHICLES CLASSIFICATION:  *** FHWA CLASS 9 0.0
	*** PERCENT "UNCLASSIFIED" VEHICLES: <u>0.0</u>
	ON LEADING CALIBRATION EFFORT:Dean J. Wolf, MACTEC

## SHEET 16 LTPP MONITORED TRAFFIC DATA SITE CALIBRATION SUMMARY

*STATE ASSIGNED ID	[317]
*STATE CODE	[ 26]
*SHRP SECTION ID	[ 0100]

# SITE CALIBRATION INFORMATION

1.	* DATE OF CALIBRATION (MONTH/DAY/YEAR) [ 10/	3/2007]
2.	* TYPE OF EQUIPMENT CALIBRATED WIM	CLASSIFIER _X_BOTH
	* REASON FOR CALIBRATION  REGULARLY SCHEDULED SITE VISIT  EQUIPMENT REPLACEMENT  DATA TRIGGERED SYSTEM REVISION  X OTHER (SPECIFY) LTPP Validation	RESEARCH TRAINING NEW EQUIPMENT INSTALLATION
4.	* SENSORS INSTALLED IN LTPP LANE AT THIS SITE (CI BARE ROUND PIEZO CERAMIC BARE F. CHANNELIZED ROUND PIEZO LOAD C CHANNELIZED FLAT PIEZO X INDUCT OTHER (SPECIFY)	HECK ALL THAT APPLY):  LAT PIEZO BENDING PLATES  ELLS _X_ QUARTZ PIEZO  TANCE LOOPS CAPACITANCE PADS
5.	EQUIPMENT MANUFACTURERIRD/ PAT Traffic	
	WIM SYSTEM CALIBRA	TION SPECIFICS**
6.**	CALIBRATION TECHNIQUE USED: TRAFFIC STREAMSTATIC SCALE (Y/N	) _X_ TEST TRUCKS
	NUMBER OF TRUCKS COMPARED	2 NUMBER OF TEST TRUCKS USED
	TYPE PER FHWA 13 BIN SYSTEM SUSPENSION: 1 - AIR; 2 - LEAF SPRING 3 - OTHER (DESCRIBE)	PASSES PER TRUCK TRUCK TYPE SUSPENSION  1
7.	SUMMARY CALIBRATION RESULTS (EXPRESSED A MEAN DIFFERENCE BETWEEN DYNAMIC AND STATIC GVW	,
8.	3 NUMBER OF SPEEDS AT WHICH CALIBRATIO	ON WAS PERFORMED
9.	DEFINE THE SPEED RANGES USED (MPH)5	0 60 70
10.	CALIBRATION FACTOR (AT EXPECTED FREE FLOW	7 SPEED)1071
11.*	* IS AUTO-CALIBRATION USED AT THIS SITE? (Y/N) IF YES, LIST AND DEFINE AUTO-CALIBRAT	
	CLASSIFIER TEST S	SPECIFICS***
12.*	** METHOD FOR COLLECTING INDEPENDENT VOLUM VIDEOX_ MANUAL	
13.	METHOD TO DETERMINE LENGTH OF COUNT	TIME X NUMBER OF TRUCKS
14.	*** FHWA CLASS 8 <u>0.0</u> FHW	ASSIFICATION: A CLASS A CLASS A CLASS
		A CLASS
	RSON LEADING CALIBRATION EFFORT:Dean J. Wolf, DNTACT INFORMATION:301-210-5105	MACTEC rev. November 9, 1999



LTPP Traffic Data	* SPS PROJECT ID 0100
*CALIBRATION TEST TRUCK #_1 Rev. 08/31/01	* DATE 10/2/2007
	those ip
PART I.	MAILGE VIZ
1.* FHWA Class 2.* Number of Axles _	Number of weight days
AXLES - units - lbs / 100s lbs / kg	
GEOMETRY	
8 a) * Tractor Cab Style - Cab Over Engine / Conventiona	al b) * Sleeper Cab? Y/N
9. a) * Make: <u>\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \</u>	- Andrewson's
10.* Trailer Load Distribution Description:	
PALLETTERS SAME OF FESTILITES CONTEST EVENT	u how yould
11. a) Tractor Tare Weight (units):	· · · · · · · · · · · · · · · · · · ·
b). Trailer Tare Weight (units):	· ·
12.* Axle Spacing – units m / feet and inches / feet a	and tenths
	NAME OF THE PROPERTY OF THE PR
A to B 19.4 B to C 4.5	C to D 32-3
D to E	E to F
Wheelbase (measured A to last)	Computed
13. *Kingpin Offset From Axle B (units) + 2.	0 (
$\frac{1}{(+ is to)}$	the rear)
SUSPENSION	
	(leaf, air, no. of leaves, taper or flat leaf, etc.
<b>7</b> 75	
Now.	
·	
F	

\* STATE\_CODE

26

Sheet 19

 $6420070022\_SPSWIM\_TO\_22\_26\_2.96\_0100\_Sheet\_19\_axle\_scales\_truck\_1.doc$ 

Sheet 19	* STATE CODE 26
LTPP Traffic Data	* SPS PROJECT ID 0100
*CALIBRATION TEST TRUCK #_1_	* DATE 10/2/2007

#### **PART II**

Day 1

\*b) Average Pre-Test Loaded weight

\*c) Post Test Loaded Weight 76020 \*d) Difference Post Test – Pre-test + 1013

vehicle refuded at 100 10 and 2160pt/2150016

Table 5. Raw data – Axle scales – pre-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10 680	13800	13 600	18340	१९३५०		74960
2	10680	13830	13830	1.8340	OVEBI		っくひてつ
3	10 680	13860	13860	18320	७ऽ१७।		75040
Average	10680	13830	13830	18333	18333		75007

Table 6. Raw data – Axle scales –

Pass Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7. Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11140	14690	14090	18350	18350		76020
2	00111	14140	14140	18320	18320		76020
3	11080	14150	14150	18320	18320		76020
Average	T 0111	14127	[4127	(%330	18330		76020

Measured By	DAN	Verified By	8110	Weight date	10/2	11 000	x01
					, ,		

Sheet 19  LTPP Traffic Data	* STATE CODE	26
*CALIBRATION TEST TRUCK # 🎉	* SPS PROJECT ID  * DATE	0100
Rev. 08/31/2001		twa 43
PART I.		trailer VIZ
1.* FHWA Class 2.* Number of Axle	s 5 Number of we	ight days
AXLES - units - lbs / 100s lbs / kg		
AXLES - units - 105/1005105 / kg		
GEOMETRY		
8 a) * Tractor Cab Style - Cab Over Engine / Convention	onal b) * Sleeper Cab? Y	/N
9. a) * Make: ** Model: b) * Model:		
10.* Trailer Load Distribution Description:	٦ ، ١ - ١ ، ١ - ١ ، ١ . ١ . ١ . ١ . ١ . ١ . ١ . ١ . ١ .	
PAUFTRED FEATILIZER BAGIS LOADED EXE	WOT ALENG TIGHTEE	
11. a) Tractor Tare Weight (units):		
b). Trailer Tare Weight (units):		
12.* Axle Spacing – units m / feet and inches / fee	et and tenths	
A to B 18.6 B to C 4.3	C to D 32.1	
D to E <u>4.1</u>	E to F	
Wheelbase (measured A to last)	Computed	
13. *Kingpin Offset From Axle B (units)	2.0 (	
(+is	to the rear)	
SUSPENSION		
	a c : c1	
	on (leaf, air, no. of leaves, taper or	
A 11225 2 for 1648  B 11225 Ml		
C 11022.5 MD		
D JSRZY, S MA		
E 75 [24,5] ML		
F		

		Sheet 19		* ST	ATE_CODE	26	
	<del>4</del>	PP Traffic Data			S PROJECT ID	0100	
		TION TEST TRU	JCK # 1&	* DA	TE 10/2/2	2007	
Rev. 08/31/0	l						
			4	Day 2	·		
7.2		Pre-Test Loa t Loaded Wei		7596	2 75440		
Гаble 5.2. 1	*	ce Post Test -	- Pre-test	<del>-521</del>	,		
Table 5.2.	*d) Differen	ce Post Test -	- Pre-test	Axle D	Axle E	Axle F	GVW
Pass	*d) Differen Raw data – Ax	cle scales – pro	- Pre-test	Axle D		Axle F	GVW 75940
	*d) Differen Raw data – Ax Axle A	cle scales – pro	- Pre-test e-test Axle C		Axle E	Axle F	
Pass	*d) Differen  Raw data – Ax  Axle A	le scales – pro	e-test  Axle C	18260	Axle E	Axle F	७५५०

Table 6.2. Raw data – Axle scales –

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1							
2							
3							
Average							

Table 7.2 Raw data – Axle scales – post-test

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	-10640	14110	14110	18290	18290		15440
2		•		,			-
3							40
Average	poyo	14110	14110	18290	18290		75440

Measured By	WCD	Verified By	Wito	Weight date	10/3/07
·	XF	·			

LTPP Traffic Data	* SPS PROJECT ID 0100
*CALIBRATION TEST TRUCK # 2 Rev. 08/31/01	* DATE 10/2/2007
PART I.	
1.* FHWA Class Q 2.* Number of A	Axles5 Number of weight days2
AXLES - units - lbs / 100s lbs / kg	TRICK 30
<b>,,</b>	WALLER VIO
GEOMETRY	
8 a) * Tractor Cab Style - Cab Over Engine / Conve	entional b) * Sleeper Cab? Y/N
9. a) * Make: b) * Model:	
10.* Trailer Load Distribution Description:	
MUETIZED GAGI UT FECTIVIZES 1 DAS	269 FUENCY ALONG TYCHLER
11. a) Tractor Tare Weight (units):	
b). Trailer Tare Weight (units):	
12.* Axle Spacing – units m / feet and inches	/ feet and tenths
A to B 17.4 B to C 4.3	C to D 32.4
D to E 4,1	E to F
Wheelbase (measured A to last)	·
13. *Kingpin Offset From Axle B (units)	* 2.2 ( )
	+ is to the rear)
SUSPENSION	
•	cription (leaf, air, no. of leaves, taper or flat leaf, etc.
	AE
·*	
•	
F	

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\* STATE\_CODE

26

Sheet 19

			* STATE_CODE 26				
		PP Traffic Data	······	'S PROJECT ID	0100		
Rev. 08/31/0		ION TEST TRU	ICK # 2	* D.	ATE 10/2/2	007	
Xev. 06/31/0	1						
PART II							
71111				Day 1			
				•			
	_	Pre-Test Loa	****	64920	<u>haa</u>		
	*	t Loaded Wei	0	64660			
	*d) Differen	ce Post Test –	Pre-test	- 320			
Table 5. Ra	aw data – Axle	scales – pre-t	est				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10860	12210	12210	14860	14860		65000
2	10820	12230	12230	14960	14860		७५०००
3	00801	12220	12220	14850	14850		64940
Average	10767	12220	122-20	14857	14657		64920
	10821M	<i>y</i>		***************************************			64980
Table 6. Ra	nw data – Axle		test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10740	24200	12100	14860	14860		64668
2							
3			<u> </u>			<u></u>	

ass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	10740	24200	12100	14860	14860		64660
2							
3							
Average	10740	12100	12100	14860	14860		64660

Table 7. Raw data - Axle scales - post-test wrong fruck

Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11140	14090	14090	18350	18350	And the first statement that the statement of the stateme	76020
2	11100	14140	24148W	18320 1	M 18320		76000
3	11000	1415W	4150	18320	18320		76020
Average	11167	14127	14127	18330	18330	The production of the contract	76020

Measured By	Verified By	Weight date	10/4	e  -	1007
-------------	-------------	-------------	------	------	------

		Sheet 19			ATE CODE S PROJECT ID	26	
	LTPP Traffic Data					0100	
L Rev. 08/31/01		ION TEST TRU	CK # 2	* DA	TE 10/2/20	07	
(CV. 00/31/0)	<u>E</u>						
				Day 2			
7.2		Pre-Test Load t Loaded Weig		65627			
	*d) Differen	ce Post Test –	Pre-test				
Table 5.2. I	Raw data – Ax	le scales – pre	-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	11280	12310	12310	14870	14870		65640
2	11300	12270	12270	14900	14900		65690
3	11120	12390	12390	)4850	14850		65600
Average	11233	12323	12323	१५ ६७३	14873		65627
Tabla 6.2 I	Raw data – Axl	la conlac _					
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
*							
2							***************************************
3							
Average							
Table 7.2 R	Law data – Axl	e scales – post	t-test				
Pass	Axle A	Axle B	Axle C	Axle D	Axle E	Axle F	GVW
1	148A00	12300	12300	14630	14830		65160
2		***************************************					
3							
	10900	17-300	12306	14830	14830		65160

Verified By Woo Weight date 10/3/67

Sheet 20	* STATE_CODE	26
LTPP Traffic Data	*SPS PROJECT ID	0100
Speed and Classification Checks * 1 of* Z	* DATE	10/ _ 2 / 2007

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
63	9	7251	62	9	60		2677	60	5
-60	norecc	vdra_P	-0 to-	9	60	9	8679	60	9
61	1.5	7534	GI	17	5.7	٤	2686	60	9
Ę (	q	7549	61	9	57	ę	9714	58	2
		7566			57	9	8725	58	8
57	9	9372	G157	9	60	8	2727	61	7
54	13	9304	54	ĹŠ	57	5	8238	58	www.
1, <u>2</u>	9	9400	58	9	66	5	2773	66	S. S.
62	9	9414	CZ.	9	59	9	8794	60	٤
55	P	9460	54	è	63	Š	9815	64	5
62	8	9473	63	F	62	9	9839	63	8
59	Σ	9481	61	9	56	5	૧૪૬૧	54	lag
59	9	9501	59	9	58	9	98G G	60	8
58	3	2504	58	7	62	5	9813	63	5
60	9	9507	G l	G	59	9	9887	60	8
64	9	9512	65	Ž.	58	2	9990	58	È
73		9519	73	5`	61	9	9895	60	q
61	9	9536	62	9	B5	15	9946	63	5
56	9	7558	SC	q	62	10	9947	63	10
63	7	9562	69	9	68	9	9963	68	9
57	9	5581	58	9	69	<u> </u>	10031	<b>7</b> 0	and a second
60	13	9586	60	10	58	ર	10069	57	?
60	9	9612	59	9	60	2	(0077	62	2
66	Ś	9645	68	5	62	6	10079	63	E
59	7	9659	60	9	65	१	1900)	CC	9
Recorded	by <u>1000</u>	hmm	Dire	ction <u> </u>	Lane _	<u>५                                    </u>	from <u>12-47</u> 14:40	to <u>/</u>	6:15

arle vell

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Sheet 20	* STATE_CODE	26
LTPP Traffic Data	*SPS PROJECT ID	0100
Speed and Classification Checks * 2 of* 7	* DATE	10/ <i>0</i> _2_/2007

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	
65	G	10104	<i>C</i> 5	9	63	ર	10454	64	9	
65	10	10134	65	10	58	5	10494	60	5	
64	7	10136	G4	9	59	9	<b>∕</b> 050₹	60	9	
62	8	10143	٤٤	8	(23)?	15	(O523_	60	7	Crawe verylan
63	9	10166	Ç4	9	53	<b>53</b> 0	<i>(0525</i>	<b>6</b> 0	(0	tiles
60	9	10182	60	9	62	9	10534	64	8	
	5	10204	7/	5	55	9	10570	55	9	
62	8	10225	62	8	$\epsilon$ (	5	10589	61	4	
C3	9	(0Z3S	6.3	9	62	9	10600		8	
62	9	10248	62	9	G P	5	10614	62	55	
62	9	10262	62	9	58	5	10631	64	5	
58	9	10264	62	9	56	5	10656	58	5	
68	5	10301	68	Same	57	10	10664	Š'?	10	
61	9	(0307	61	9	60	5	10675	61	5	
٤(	Q	(0313	CŽ	?	63	9	10752	65	9	
65	2	10340	65	9	60	ç	10755	6.5	9	
58	7	10343	60	9	63	10	10778	65	10	
64	9	10359	64	q	57	5	(0)20	58	5	
56	9	10377	56	9	61	5	10868	6(	4	
60	2	10379	EL	9	58	10	10890	518	10	
59	9	10416	GL	9	63	5 /	0897	63	ef	
e l	9	10417	<i>(</i> 2	9	64	5	10838	64	5	
57	10	10428	57	10	56	12	10857	56	12	
64	.5	10434	65	5	61	7	1098 l	Gl	9	
65	.5	10446	<i>CS</i>	S	54		(0997	54	G	

Recorded by J Kramer

Direction \_ Lane \_ Time from \_14:40 to \_16:15

5/4 problems lengther weight

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Sheet 20	* STATE_CODE	. 26
LTPP Traffic Data	*SPS PROJECT_ID	0100
Speed and Classification Checks * 2 of*2	* DATE	10 <u>/_53</u> /2007

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM	WIM Record	Obs. Speed	Obs Class
é8	Ç	10641	20	G	63	9	11078	64	P
~70	4	10692	05	4	62	ID	11098	63	10
43	Q	(0763	63	f	64	9	11114	64	9
64	q	10714	64	વ	63	8	11118	63	き
59	9	10727	60	9	63	9	illao	63	9
64	(3	10730	65	13	67	Ĝ	11235	67	9
60	q	10744	60	9	58	G	11252	59	6
5.9	q	(0759	59	q	59	6	11287	59	Č
59	8	10782	58	E	56	S	i 1300	57	5
67	5	10195	67	5	62	10	11312	62	10
61	9	10827	62	9	63	9	11352	63	Q
59	13	10845	58	10	<u> Š</u>		11359	60	रि
63	13	10868	63	13	ÇÓ	9	11369	61	ય
59	<u>C</u>	10885	59	6	66	Ġ	1/37/	66	9
<u> </u>	5	10834	59	5	59	<u> </u>	11413	60	9
70		10918	70	5	6 (	5	11415	GŽ	S
GL	9	10951	62	G	59	q	11425	60	9
71	5	(0960)	71	5	60	5	11438	61	5
G.G	5	10965	Gq	S	SY	9	11474	56	9
70	5	1880/	70	,5	Gl	9	11513	62	9
57	9	1(026	5° ° ° ° ° ° ° ° ° ° ° ° ° ° ° ° ° ° °	9	59	5	11517	60	5
G1	9	11036	G(	9	60	5	11536	61	Angel To
63	9	11059	<i>43</i>	$\mathcal{G}$	63	<u> </u>	11569	62	5
62	9	11068	63	9	63	5	[1582	63	S*
63	6	11073	<i>6</i> 3	Č	62	9	11589	62	8
Recorded	ال کا ا	<u> </u>	Dire	ection	Lane	니_Time	from <u>7:35</u>	to L	14

Sheet 20	* STATE_CODE	26
LTPP Traffic Data	*SPS PROJECT ID	0100
Speed and Classification Checks * _ \ of* \ _	* DATE	

WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class	WIM speed	WIM class	WIM Record	Obs. Speed	Obs Class
63	9	9750	63	9	58	8	/025§	59	q
63	9	9780	63	9	59	S	10294	59	4
62	9	9781	63	Ä	61	9	10315	62	9
65	G	9790	66	9	63	5'	(0320)	Ld	G.
<u>"11</u>	5	9793	ĆŚ	, Le C	60	9	10353	65	8
G (	13	9919	<b>6</b> 3	15	59	Š	10338	Sq	5
58	9	9926	59	9	28	Ĝ	10333	5.8	9
58	10	9929	5 9	10	56	Ÿ	10401	5 7	9
65	9	9946	<b>C</b> S	Ŝ	58	G	10416	57	q
63	q	9947	63	9	65	P	10421	65	9
<u>65</u>	5	9976	65	5	49	C.	10.(28	2( S	Ŝ
53	8	10002	60	8	60	9	10462	G L	q
57	£	10038	57	વ	68	S	10470	G K	کہ
59	q	10037	59	9	63	E	10515	63	9
GL	8	10046	6 l'	3	57	10	10534	58	/Ö
59	10	10029	55	10	66	6	10552	66	Ĝ
60	(3	10091	60	13	GŠ	\$	10556	G Ś	
63_	10	10109	62	10	SY	q	10562	54	4
61	9	10112	63	q	63	5	10568	63	Served Served
54	q	10118	54	q	61	9	102.73	G1	q
<u> 59</u>	13	1015(	25	1.3	60	5"	10576	60	5
67	9	10169	68	9	58	q	10584	61	Q
56	$\overline{q}$	10188	55	9	C (	$\epsilon$	10568	61	9
58	10	10224	58	10	59	6	10621	59	6
62	9	10341	61	q	58	e-roy Curi	10636	59	S
Recorded	by <u>1</u> K	***	Dire	ction <u></u>	_ Lane _	۲ Time f	from <u>2:35</u>	_ to <u>_4</u>	114

				H-H	spac	,	
,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,				D H	space	9	سد. سومین سرمین
26	0100			Q.O	space	23	o co
	0	10/ 02 / 2007		B-C	space	60.2 My 4.3 32.3	
		10 / 01		A-B	space	Z.	
ODE	CT_ID			GVW		40,2	5
ATECC	*SPS PROJECT_ID	* DATE		Axle F	weight		
LS *	*SP	* D/		Axle E	weight.	7	<u>}</u>
				Axle C Axle D	weight.	9.5	<u>م</u>
				Axle C	weight.	9	), Jan
				Axle B	weight.	3.1	300 × 500 ×
		to 1		Axle A	weight.	Em.	5 5
	c Data	cords		MIM	Speed	5	Ž,
Sheet 21	PP Traffi	Truck Re		Record	O	4334	
	LTPP Traffic Data	tem Test		Time		) 37	
		WIM Sys		Pass		, where the	- Marie
				Truck		C)	<sub>k</sub> , sieh
1			/31/2001	Radar	Speed	3	5
			Rev. 08/31/2001	Pvmt	temp	100 mm	

E-F space																
D-E space	9 5	ingeneral Sangari anna	0	9	o J	٥ ت	0.7	ن خ	0,7	0 J	٥	o	O h	٦. ا	yeare 	0
C-D space	32.3	2,5	32.3	32.0	32.3	5.	72.4	22.0	32.3	1.75	75 H	32.0	32.2	32.0	T.	32.0
B-C space	6.3	تر بر	m J	ان ا	4.3	ガ	4.3	Sh	4.3	#. h	くり		7.3	j.		l,
A-B space	7.	S	T rui	T		S. Contraction of the Contractio	£ \$	7	Ţ	19.4	5.1	ă.	ナニ	19.3	~ ~	63
€WM	ko.2	5	<u>من</u> مـــٰـ	5.3	52.V	۰۰۰ فه و	54.1	( B.4	51.3	ن.کی	8.3	68.4	3	<b>(8</b> .4	77. 09. 20.	رد دم (۲
Axle F weight											į					
Axle E weight.	14.1	7.	or 	ž	7.21	0	13.7	5.3	00 2	2:51	¥. 2.	1.3	13.3	16.2	igua e Sir	Ľ.
Axle D weight.	b) . c.	8.3	13.0	て,	12.3	2	3.5	£ U	12.5	0.9	<u>6</u> -	P, SI	3.7	7	3,5	2.5
Axle C weight.	7.9	) <u>;</u>	9	9	STATE OF THE STATE	2.5	A LEEDWAY 	ingeren Seanne	õ	ري- ي	: e	1:1	10.5	7, 7	9	۵.e ئىر
Axle B weight.	<u>٠</u>	13.0	13 June	9.1	<u>0</u> يې	5.3	50	13.5	محتدو. المحاضمين المحاضين	9:71	ુ. છે.	1.7	10.7	13.6	90	p.A.
Axle A weight.	E	2	0.0	20	a_ oo	<u>5</u>	9.9	ر م	7. 3	60 60	رت 00	9	رة. م	(j-)	2.0	و و
WIM Speed	S	ß	R	TV.	52	<i>00</i>	2 2	S	ار د	22	ę	್ತಿ	5	S	5	25
Record No.	4339		Ş	45.3%		3 3 7	a fight	4853	SDC 6	2015	5178	5181	3 3	54 4 S	さ <u>い</u>	1125
Time	केंग्र	d d	2.53	45.5	10:04	5 5 5 72	7.0	51:0	(0:2 <b>6</b>	<b>1</b> (10)	3.0	16:51	6:57	(c:5)	11:08	100
Pass	, popularies		М	N	in	W	1305	Vinger	V	1./	و	و	ŗ	(**	90	တ
Truck	r)	s, watch	r.s	Assessed	2	ant was	7	sures.	61	والمستون ا	И		ſΝ	)samet a land	2	wine:
Radar Speed	30	5	S.	3	65	00 C		2	7.9	8	Š	٥	10	S	Ď.	9.S
Pvmt temp	5	Sant Sant	5	S. S.	(H.S	Š	15	65	Z. 2	S ha	45,5	65.5	3,	0.53	64.5	64.5

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garet e				Space												
				D-E space	0	O J	٥.٢	0	ø,	0	j	o Í	0	0	٥ خ	o J
26	0100			C-D space	7. 7.	32.0	27.3	31.9	32.3	2.	32.3	ر س	32.4	31.5	32.3	32.0
	0	2-/2007		B-C space	r.	سرن سرن	u,	ュバ	7.	ブ	4.3	ゴ	4.3	だん	M T	ير عر
		10/0		A-B space	r.	<u> </u>	エロ	ã. L	ナご	2.5	5'11	ر. ا	Sin	HEI	***	4.61
CODE	CT ID			@vW		<b>6</b> 89	82 4	(H-)	2.1.2	S	2.95	%	7.95	6.19	L:LS	و د
STATE CO	*SPS PROJECT	* DATE		Axle F weight												
*	*SP	* D		Axle E weight.	7.2	 	13.0	15.9	-3·6 -3·6	9	12.3	5. %	13.8	7.51	8-2)	2
				Axle D weight.	7	3	 	2	0	J. 3	2 []	5.8	5.0	Z.	5.5	5.3)
				Axle C weight.	11.3	d.	<u>0</u>	1.7.1	7.01	Ç	8.01	0.5	I: o	12.3	13	5.2
		C-V		Axle B weight.	<u>0</u>	5.50	<u>0</u>	6.0	j	Č		5.2	444	1	F.01	10.3
		2 of		Axle A weight.	0.0	- -	r s	2,	Ğ	(0.3	5	<u>წ.</u>	0°	تر <b>ن</b>	<u>Q</u>	ħ: 01
	c Data	cords		WIM Speed	3	ご	R	20	٥ ع	So	5	ち	S	S		95
Sheet 21	LTPP Traffic Data	Truck Re		Record No.	2000	7,527	6037	6043	7	1449	9291	7639	LA	SP	7435	1451
	LI	WIM System Test Truck Records		Time	61:11	\$1.11   11.11	7.52	23	SS:21	12:52	50.0	13:09	13:19	D. G.	27.67	08:81
		WIM Sys	•	Pass	5	0	0	9	سمير. وانسر	مسينين. المسينين	~	7	~^	~	5	I
				Truck	n	لمنميس	ÇĴ	epilintek	ţ.i	سينور.	2	speld	H	dumiyyyi	Ų	Acers
			Rev. 08/31/2001	Radar Speed	S.	<u>ر</u>	R	3	Š	55	9		S	3	Ŝ	28
			Rev. 08	Pvmt temp	5	5	Prince !	E.		9	<u>, - 1</u>	i,	ind Parasas	Ť	72	<u></u>

Checked by

Recorded by Naw

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31.6

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Sheet 21	LTPP Traffic Data	Truck Re	Record	No.	2250	g255	<b>S</b> S S	36.86	88 73	ر ا ا	2516	\$ (5) \$ (5)					
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CODE	CT ID		·* ·	0,000	64.1	75.3	Ú6.1	74.5	C.4.7	7.7.	8.57	2.	ر <del>د</del> با	Ę	5:59	76.5
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Sheet 21	LTPP Traffic Data	Truck Re	i	Record No.	4014	4017	4169	400	परश्य	43%	bl hh	4482	4615	4631	0814	thall h
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			31/2001	Radar Speed	75	<u>م</u>	٥٥	09	5	ور	Š	B	07)	00	e c	S
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WIM System Test Truck Records   lof 2   lof 3   lof 2   lof 3   lof						Sheet 21	7					TS*	* STATE CODE				26		
Poss   Time   Record   Milm   Axie Axie B   Axie C   Axie D   Ax						PP Iraiii	c Data					%SPC	*SPS PROJECT			1	0100		
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10:11   4837   5:1   1:11   12.4   12.3   15:2     8   10:24   5:12   6:0   11.2   14.3   14.2   14.3     9   10:34   5:36   6:0   12.1   14.3   14.2   14.1     10:34   5:36   6:2   11.1   12.1   12.1   13.1     10:34   5:36   5:2   14.3   14.1   15.1   14.1     10:34   5:36   5:3   14.1   14.1   15.1   14.2     10:45   5:49   5:1   10.4   13.1   13.1     10:46   5:49   5:1   10.1   13.3   13.2     10:46   5:49   5:1   10.1   13.3   13.2     10:47   5:49   5:41   13.1   13.1     10:56   5:49   5:41   13.1   13.1     10:57   5:49   5:41   13.1   13.1     10:51   5:49   5:5   16.5   16.5     11:31   5:41   5:41   5:41   5:41     11:33   5:42   5:41   5:41   5:41     11:33   5:41   5:41   5:41     11:34   5:45   5:45   5:45     11:51   5:41   5:41   5:41     11:35   5:45   5:41   5:41     11:37   5:45   5:45   5:41     11:38   5:45   5:45   5:45     11:41   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:31   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41   5:41   5:41     11:41   5:41   5:41   5:41   5:41   5:41   5:41     11:41   5:41	Speed		<del>*************************************</del>	es Se Se	ПТЕ	Kecord No.	Speed	Axle A weight.	Axle B weight.	Axle C weight.	Axle D weight.	Axle E weight.	Axle F weight	MV.9	A-B space	B-C space	C-D space	D-E space	E-F space
8 10.24 5.81 6.0 11.7 11.0 12.10 13.5 52.01 8 1 1.91 1.21 2.11 6.0 11.5 52.01 11 1 1 1.21 1.21 1.21 1.21 1.21 1.2	B		r.s	<b>f</b>	11:0)	F. 83.	N	- marketin T - marketin (marketin)	12.4	ا ہے ا	2:51			68 C S	5	Š	32.3		
8 10:23 5:21 60 11:5 12:2 14:3 14:2 17:0 8 9 10:24 5:40 60 12:2 14:3 14:2 17:0 17:0 17:0 17:0 17:0 17:0 17:0 17:0	or		بالمعتبين	<u> </u>	10	4985	one Colombia	2.11	五	13.3	φD	oc.		0.5	.9 2	ガ	32.0	o Ť	
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Sheet 21		* STATE CODE	26
LTPP Traffic D	Data	*SPS PROJECT ID	0100
WIM System Test Truck Recon	rds 2 of 2	* DATE	10/ 0 3 / 2007
Rev. 08/31/2001			

E-F space														1	
D-E space	<i>්</i>	, tr	o. T	o	o j	20	j.	٦. ٥.	0.4	o J	0 T	٥. خ			
C-D space	2.25	o-	32.2	5. N	32.3	- N	h.28	31.9	32.3	32.0	77.7	2.8			
B-C space	~ **	M.	N. T.	M J	L'S	7.	4.3	4.3	7.	rv T	7.7	t t			
A-B space	7.3	-8.e	て こ	⊗ 3.	7.	گ <del>ن</del> ال	11.5	99	Ç	9.00	J	9.81			
GVW	C.H.J	2.3	65.6	7.3	67.6	73.0	5	00 T	ئام)	J S. 00	0.99	2.2			
Axle F weight															
Axle E weight.	<u> </u>	C	N. H.	5.83	ي ق	2	N. N.	r. C	2.5	0	0,9	7.			
Axle D weight.	Z. 7.	j	Ţ	0.00	65.6	GC	N. T.	P. U	H.2	ر ن ن ن		2.9			
Axle C weight.	12,2	0 1	12.5	الله و	8	13.0	12.6	0.7)	6.21	(3.0	0	5.50			:
Axle B weight.	12.3	ひず	13.5	エヹ	d.	7,7	2.5	7.11	0,21	三三	6.11	13.6			
Axle A weight.	9.1	Ÿ	<b>1</b>	12.0	ナニ	p. 0.	50	11.3	L. ).	magarian and i	100	~~			
WIM	.9	λ a_	00	00 e.	ß	S	25	3	ور	66	S	S			
Record No.	HEZL	7255	507	97 H.Z	<u>2</u> 2	209	7769	00011	1931	1977	\$ \$ \$	3			
Time	12:37	12.30	87.2	bh:21	35:20	15:21	13:0A	3:10	2:18	13:21	13:29	13.31			
Pass	7	ñ	2	.9			/9O	00	5	5	R	2			
Truck	ائم	Summer	Ç	bostopes.	ال3	*AMETPER*	٦		(1		6-1	n garbaniji			
Radar Speed	00	ري د	5	00	ଝ	5	5	3	Q <u>&amp;</u>	િ	S.	wa.			
Pvmt temp	S. 28	Š		55	(J)	50	\$P	90 J	S.	5.5	.g.	33			

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Calib	ration	Wor	ksheet
		, , ,	

Site: \_\_260100\_\_\_\_

Calibration Iteration / Date 10[3]07

**Beginning factors:** 

Speed Point (mph)	Name	Value
Overall	o ver il	82.0
Front Axle	Sout was	1039
1 – ( 4570 )	CF 1	Į000
2 - (60)	2	(0,4
3-(70)	3	1044
4-( )	liero l	960
5 – ( )	ails 2	1040

#### **Errors:**

	Speed	Speed	Speed	Speed	Speed Point 5
	Point 1	Point 2	Point 3	Point 4	Point 5
F/A	- 8.9	-6.2	-6.5		
Tandem	-9.8	-12.9	( ) 1		
GVW	-9.6	-11.8	-11-2		

## Adjustments:

•	Raise	Lower	Percentage
Overall	X		8.8
Front Axle			
Speed Point 1	minimum of the second		Charles of the Control of the Contro
Speed Point 2			9+19-13-57 3.6 %
Speed Point 3			8-9-1, 12.2 to 2.6 %
Speed Point 4			
Speed Point 5			

### **End factors:**

Speed Point (mph)	Name	Value
Overall	1133 840	200 900
Front Axle	hort dule	1054
1-(50)	r fr (	14875 1000
2-(60)	2.	11501050
3-( 📆 )	3	127 107 L
4 – ( )	N. 62.92 L	~16 <i>v</i>
5-( )	2	1040

# TEST VEHICLE PHOTOGRAPHS FOR SPS WIM VALIDATION

October 2-3, 2007

STATE: Michigan

**SHRP ID: 0100** 

Photo 1 - Truck_1_Tractor_ 26_0100_10_02_07.JPG	. 3
	. 3
	. 3
Photo 4 - Truck_1_Suspension_2_26_0100_10_02_07.JPG	
Photo 5 - Truck_1_Suspension_3_26_0100_10_02_07.JPG	
Photo 6 - Truck_2_Tractor_26_0100_10_02_07.JPG	. 4
Photo 7 - Truck_2_Trailer_26_0100_10_02_07.JPG	
Photo 8 - Truck_2_Suspension_1_26_0100_10_02_07.JPG	
Photo 9 - Truck_2_Suspension_2_26_0100_10_02_07.JPG	
Photo 10 - Truck_2_Suspension_3_26_0100_10_02_07.JPG	
Photo 11 - Truck_1a_Tractor_ 26_0100_10_03_07.JPG	
Photo 12 - Truck_1a_Trailer_1_26_0100_10_03_07.JPG	
Photo 13 - Truck_1a_Suspension_1_26_0100_10_03_07.JPG	
Photo 14 - Truck_1a_Suspension_2_26_0100_10_03_07.JPG	
Photo 15 - Truck_1a_Suspension_3_26_0100_10_03_07.JPG	



Photo 1 - Truck\_1\_Tractor\_ 26\_0100\_10\_02\_07.JPG



Photo 2 - Truck\_1\_Trailer\_1\_26\_0100\_10\_02\_07.JPG



Photo 3 - Truck\_1\_Suspension\_1\_26\_0100\_10\_02\_07.JPG



Photo 4 - Truck\_1\_Suspension\_2\_26\_0100\_10\_02\_07.JPG

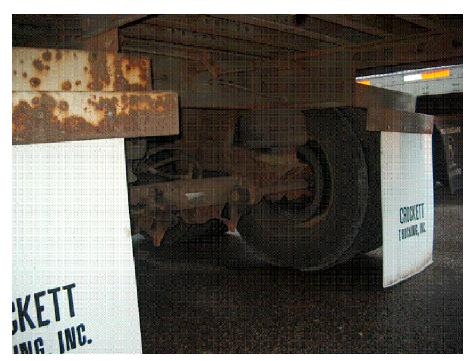


Photo 5 - Truck\_1\_Suspension\_3\_26\_0100\_10\_02\_07.JPG



Photo 6 - Truck\_2\_Tractor\_26\_0100\_10\_02\_07.JPG



Photo 7 - Truck\_2\_Trailer\_26\_0100\_10\_02\_07.JPG



Photo 8 - Truck\_2\_Suspension\_1\_26\_0100\_10\_02\_07.JPG



Photo 9 - Truck\_2\_Suspension\_2\_26\_0100\_10\_02\_07.JPG



Photo 10 - Truck\_2\_Suspension\_3\_26\_0100\_10\_02\_07.JPG



Photo 11 - Truck\_1a\_Tractor\_ 26\_0100\_10\_03\_07.JPG



Photo 12 - Truck\_1a\_Trailer\_1\_26\_0100\_10\_03\_07.JPG



 $Photo~13-Truck\_1a\_Suspension\_1\_26\_0100\_10\_03\_07.JPG$ 



Photo 14 - Truck\_1a\_Suspension\_2\_26\_0100\_10\_03\_07.JPG



Photo 15 - Truck\_1a\_Suspension\_3\_26\_0100\_10\_03\_07.JPG

Michigan Dept of Transportation Classification and Weight Parameters for WIM

Class	Vehicle Description	# axles	Spacing 1	Spacing 2	Spacing 3	Spacing 4	Spacing 5	Spacing 6	Spacing /	Spacing 8	Spacing 9	Spacing 10	Weight Min-Max
1	Motorcycle	2	0.1-6.0										100-3000
2	Car	2	6.0 - 10.1										1000-8000
3	Truck	2	10.1-16.0										1000-8000
4	Sng	2	21.09-40.0										12000 >
2	Ω7	2	8.0-21.09										< 0008
2	Car / 1 Axle Trailer	3	6.0 - 10.1	6.0-30.0									1000-12000
3	Truck / 1 Axle Trailer	3	10.1-16.0	6.0-30.0									1000-15000
4	Bus	3	21.09-40	3.0-7.0									20000 >
5	2D / 1 Axle Trailer	3	8.0-21.09	6.3-30.0									15000-12000
9	3 Axle Single Unit	3	8.0-26.0	2.5-6.3									12000 >
8	Semi 2-1	3	8.0-23.09	11.0-40.0									20000 >
2	Car / 2 Axle Trailer	4	6.0-10.1	6.0-30.0	1.0-11.99								1000-12000
3	Truck / 2 Axle Trailer	4	10.1-16.0	6.0-30.0	1.0-11.99								1000-15000
5	2D / 2 Axle Trailer	4	8.0-23.09	6.3-30.0	1.0-11.99								15000-20000
7	4 Axle Single Unit	4	8.0-23.09	2.5-6.3	2.5-13.0								12000 >
8	Semi 2-2	4	8.0-23.09	11.0-45.0	2.5-11.99								20000 >
8	Semi 3-1	4	8.0-26.00	2.5-6.3	6.1-45.0								20000 >
3	Truck / 3 Axle Trailer	5	10.1-16.0	6.0-30.0	1.0-11.99	1.0-11.99							1000-15000
7	5 Axle Single Unit	5	8.0-23.09	2.5-6.3	2.5-6.3	2.5-6.3							12000 >
6	Semi 3-2	5	8.0-26.0	2.5-6.3	6.0-45.0	2.5-27.0							20000 >
6	Semi 2-3	5	8.0-23.09	11.0-45.0	2.5-6.3	2.5-6.3							20000 >
[1	Semi 2-1-2	5	8.0-26.0	11.0-26.0	6.0-20.0	11.0-26.0							12,000 >
10	Semi 3-3	9	8.0-26.0	2.5-6.3	6.1-45.0	2.5-11.99	2.5-11.99						20,000 >
10	Semi 2-4	9	8.0-23.09	11.0-45.0	2.5-6.3	2.5-6.3	2.5-6.3						20,000 >
10	Semi 4-2	9	8.0-26.0	2.5-6.3	2.5-6.3	6.1-46.0	2.5-11.99						20,000 >
12	Semi 3-1-2	9	8.0-26.0	2.5-6.3	11.0-26.0	6.0-24.0	11.0-26.0						12,000 >
10	Semi 3-4	7	8.0-26.0	2.5-6.3	10.0-20.0	6.0-12.0	6.0-12.0	6.0-12.0					20,000 >
10	Semi 3-4	7	8.0-26.0	2.5-6.3	3.5-45.0	2.5-12.0	2.5-6.3	2.5-6.3					20,000 >
13	Semi 3-*-*	7	8.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0					20,000 >
10	Semi 3-5	8	8.0-26.0	2.5-6.3	3.5-45.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3				20,000 >
10	Semi 3-5	8	8.0-26.0	2.5-6.3	10.0-20.0	6.0-12.0	2.5-6.3	2.5-6.3	2.5-6.3				20,000 >
13	Semi 3-*-*	8	8.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0				20,000 >
10	Semi 3-6	6	8.0-26.0	2.5-6.3	3.5-45.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3			20,000 >
10	Semi 3-6	6	8.0-26.0	2.5-6.3	10.0-20.0	6.0-12.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3			20,000 >
10	Semi 4-5	6	8.0-26.0	2.5-6.3	2.5-6.3	6.3-15.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3			20,000>
13	Semi 3-*-*	6	8.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0			20,000 >
10	Semi 3-7	10	8.0-26.0	2.5-6.3	3.5-45.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3		20,000 >
10	Semi 3-7	10	8.0-26.0	2.5-6.3	10.0-20.0	6.0-12.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3		20,000 >
10	Semi 4-6	10	8.0-26.0	2.5-6.3	2.5-6.3	6.3-15.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3		20,000>
10	Semi 5-5	10	8.0-26.0	2.5-6.3	2.5-6.3	2.5-6.3	6.3-15.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3		20,000>
13	Semi 3-*-*	10	8.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0	3.0-45.0		20,000 >
10	Semi 3-8	11	8.0-26.0	2.5-6.3	3.5-45.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	20,000 >
10	Semi 3-8	111	8.0-26.0	2.5-6.3	10.0-20.0	6.0-12.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	20,000 >
10	Semi 5-6	11	8.0-26.0	2.5-6.3	2.5-6.3	2.5-6.3	6.3-15.0	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	2.5-6.3	20,000>
7	Com: 3 **	-	0 4 0 0	30.45.0	30.450	0 47 0 0	0 4 7 0 0	0 0		0 47 0 0	0 47 0 0	0 0	0000

### System Operating Parameters

### Michigan SPS-1 (Lane 4)

October 2, 2007	July 11, 2006
900	820
1039	1039
1000	1106
1050	1150
1071	1171
960	960
1040	1040
	900 1039 1000 1050 1071 960